

GEOMETRIC CONSTRAINTS II

Realizability, Rigidity and Related theorems.
Embeddability of Metric Spaces

Section 1

Given the matrix D $d_{i,j}$ $1 \leq i,j \leq n$ corresponding to a metric space, give conditions under which this matrix can be realized as pairwise distances between points in R^d

Theorem: M is positive semidefinite of rank $d \Leftrightarrow D$ can be realized in R^d

Proof : (\Leftarrow) Consider $n+1$ points in R^d with one of them being the origin. Let X be the matrix of their co-ordinates. Take the gram matrix $G = G_{i,j} = \langle p_i, p_j \rangle = X^T X$ ($n \times n$ matrix). $G_{i,j} = (d_{o,i}^2 + d_{o,i}^2 - d_{i,j}^2)$. G is positive semi-definite and has rank d ;

(\Rightarrow) Since M is positive semidefinite of rank d , there exists an orthonormal Y . $L = Y^T M Y \Rightarrow X = L^{1/2} Y$; X has only d non zero rows. Now take the gram matrix of X , $X^T X = Y^T L^{1/2 T} L^{1/2} Y = Y^T Y M Y^T Y = M$. It results that $M = 1/2(|p_0 p_i|^2 + |p_0 p_j|^2 + |p_{i,j}|^2)$ for some set of points p_1, p_2, \dots, p_n which form the rows of X . The realization X can be obtained in $O(n^3)$ steps.

*Volume of n points can be obtained as a determinant. In 2D a 4 point volume has to be 0.

Necessary Conditions: (*Cayley Menger Conditions*)

Suppose you are given a distance matrix $(n+1) \times (n+1)$ in R^k space.

$$\begin{bmatrix} 0 & 1 & 1 & 1 & 1 & \dots \\ 1 & 0 & d_{12} & d_{13} & \dots & d_{1n} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ 1 & d_{n1} & d_{n2} & \dots & \dots & \dots 0 \end{bmatrix}$$

Then the cayley-menger condition requires that the volume of the $k+2$ simplex to be zero. $\forall k+2$ simplex spanned by $(P_1 \dots P_{k+2})$ $Vol_{k+2}(P_1 \dots P_{k+2}) = 0$

$$\begin{bmatrix} 0 & 1 & 1 & 1 & 1 & \dots \\ 1 & 0 & d_{12} & d_{13} & \dots & d_{1k+2} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ 1 & d_{k+21} & d_{k+22} & \dots & \dots & \dots 0 \end{bmatrix} = 0$$

The other condition is that the volume of all smaller simplices formed by $K+1$ points in the set should be positive.

$\forall j < k+1$ simplex spanned by $(P_1 \dots P_j)$ $\text{Vol}_j \text{Simplex}(P_1, \dots, P_j) \geq 0$

$$\begin{bmatrix} 0 & 1 & 1 & 1 & 1 & \dots \\ 1 & 0 & d_{12} & d_{13} & \dots & d_{1k+2} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \cdot & \cdot & \\ 1 & d_{k+21} & d_{k+22} & \dots & \dots & \dots 0 \end{bmatrix} \geq 0$$

Home Work : Are the above conditions sufficient ?

Section 2

Some Questions:

1. Why do we think about realizations as distances (not as points)?

Hint-Theorem: Pairwise distance polynomials form the entire generator set for RE_d .

2. What is the relation between the set of embeddings of n points in R^d and the set of pairwise distance matrices?

3. Is there a function mapping from one of these sets to the other, is it one to one ?

Klein's Program: Find polynomials that are invariant under the action of the euclidean group. (They are called the Ring of invariants of the euclidean group).

Ex: Prove that the distance between any two points in 2d is invariant under any Euclidean Transformation.

Hw: Prove the above in any dimensions.

Question: Fact: We know that $nd - (d+1)/2$ entries of the matrix D are

needed to derive the remaining ones. Which are these distances ?

Proof for the fact: The possible movements of the vertices in d space, for a set of n vertices is nd (independent motions). However a d dimensional rigid body in d space has d translations and $d(d-1)/2$ rotations. The total number of allowed motions is the number of total degrees of freedom nd minus the number of rigid body motions ($d + d(d-1)/2$).

For 2 dimensions, we have an answer to this question.(Lamans Theorem, which says that every subgraph should have at most $2n - 3$ edges for n vertices, and the entire graph should have $2n - 3$ edges exactly.)

Formal Statement Of Lamans Theorem: Let a graph G have exactly $2n-3$ graph edges, where n is the number of graph vertices in G . Then G is "generically" rigid in R^2 iff $e' \leq 2n' - 3$ for every subgraph of G having n' graph vertices and e' graph edges. For a proof of this refer to Geometric Constraints I Notes.

Note: In any dimension, if a body is rigid it obeys the laman count. But if it obeys the count, its not sure if it is rigid.

Question: Given such a well constrained graph, and these distances, show how to construct the remaining distances.

Question: How to construct the embedding, i.e, the co-ordinates of the other points ? Given all D: Fix 2 points and then use circles to construct the remaining.

Lemma: A transformation M satisfies $d(x) = d(Mx)$ iff M has the property of orthonormality. ($M^T M = 1$)

Theorem: A polynomial $P(x)$ is invariant wrt E_d iff $P \in R(d)$ (Pairwise dist polynomials). A configuration or an n point set in R^d is a point $\in R^n d_d$ or a distance matrix d with rank d . So the dimension of the configuration space is $nd - (d + 1)C_2$;

Problem: From the distance matrix generate one point configuration. *Algorithms:* 1.Gram Orthonormalization matrices. 2.Ruler and compass construction.

Section 3

Jackson and Jordans Theorem: If $G = (V,E)$ is 1.Redundantly rigid and 2.is 3-connected then G has a unique embedding. The converse is not true for all dimensions. (For a proof of this refer to Geometric Constraints Part 1 Notes.

Definition: Redundant Rigidity: Removal of any edge maintains rigidity.

Application: Given a bag of $\binom{N}{2}$ distances, there is always one distance matrix that satisfies these distances.

Algorithm: Build an arbitrary matrix with the initial values. verify CM conditions, when false \rightarrow permute (rows,columns)

Section 4

Schoenberg1: A metric space is embeddable into an inner product space iff it has 2-negative type.

Definition: p-negative type : A metric space $d = d_{i,j} \ 1 \leq i, j \leq n$ has p-negative type if for every $n \in \mathbb{N} \forall \alpha_1 \alpha_2 \alpha_3 \dots \alpha_n \in \mathbb{R}, \sum \alpha_i = 0$ then

$$\sum d_{i,j}^p \alpha_i \alpha_j \leq 0.$$

Fact : A space has p-negative type \Rightarrow it has q-negative type for all $q \leq p$.
Proof: Suppose for some $q < p$, the space does not have a q-negative type, but

has a p negative type. $\Rightarrow \sum d_{i,j}^q \alpha_i \alpha_j \geq 0$ for some set of alphas. But this would imply that for that same set of α_i 's we have $\sum d_{i,j}^p \alpha_i \alpha_j \geq 0$ which is against our assumption. We have a contradiction.

Schoenberg2: A normed space is isometrically embedded into an inner-product space iff the metric induced by the norm has 2-negative type.

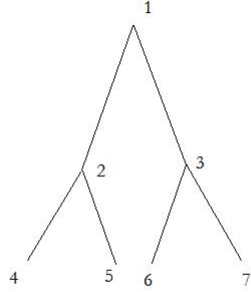
Definition: A Tree metric space is one obtained by taking vertices of a tree as points and the path length along tree edges as the metric distance between 2 points.

Fact : Any tree metric space is isometrically embeddable into L_1

BKW: A metric space is embeddable into $L_p, 1 \leq p \leq 2$, iff d has p-negative type.

Fact : Tree metric space have 1-negative type.

Hint: We can prove this by assigning every point in the tree with a co-ordinate. The points numbered in this tree are assigned a co-ordinate like this



1. [000000 00]
 2. [10000000]
 3. [01000000]
 4. [10100000]
 5. [10010000]
 6. [10101000]
 7. [101001..... 00]

Notice that this kind of assignment is consistent with the tree metric, and we can always cook up co-ordinates like that. And hence it's always possible to embed the tree metric into L_1 .

Bourgain: Tree metric spaces do not have 2-negative types, hence they cannot be embedded into L_2 without distortion.

Conjecture: Tree metrics have p -negative type for $p = 1 + \epsilon$ where $\epsilon \rightarrow 0$ as $n \rightarrow \infty$

Fact: If a metric space of n points is embeddable into L_p^k , then it is embeddable into L_p^{n-1} .

Proof: Suppose you could embed n points in L_p , think of one of the points as the origin and the rest of the points can form vectors with respect to this origin. Now, we can think of these $n-1$ vectors as forming a basis for the $n-1$ space (this is the max space that these vectors can span).