

Geometric Constraint Lecture(Mar 21-30)

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1 Problem Categories

2 Five Questions

1. **Given graph G , characterize d for which (G, d) has a realization.**
Here d are constraints, for example distance constraints.
2. **Given graph G and constraints d , provide a realization.**
3. **Given graph G , generically classify it into two categories:**
 - It has finite number of realizations.
 - One realization
 - Many realizations
 - It has infinite number of realizations.
4. **Given G , generically characterize the realization space.**
5. **Given nongeneric G , with fixed or restricted d , answer question 3 and 4. Give the classification and description of its realization space.**

3 Working on these Five Questions

3.1 Question 1

Problem: G is a complete distance graph, find $\{d : (G, d) \text{ has a realization in } \mathbb{R}^k \text{ space}\}$.

Theorem: Cayley-Menger conditions are the necessary and sufficient conditions that (G, d) has a realization in \mathbb{R}^k space.

3.2 Question 4

Question 1 and 4 are equivalent in the sense that if we understand one of them, we understand the other.

3.3 Question 3

3.3.1 Laman's theorem: A graph G generically has only finitely many solutions iff the following two conditions hold:

1. $\forall \text{subgraph } S \subseteq G, 2|V_S| - |E_S| \geq 3$
2. $2|V_G| - |E_G| = 3$

3.3.1.1 General Laman theorem: A graph $G = (V, E)$ generically has at most finitely many solutions iff $\exists \text{subgraph } G' = (V, E')$ with $E' \subseteq E$ such that

1. $\forall \text{subgraph } S \subseteq G', 2|V_S| - |E_S| \geq 3$
2. $2|V_{G'}| - |E_{G'}| = 3$

3.3.1.2 Definition of Generic

Embedding: can be understood in the following three ways:

- $(x_1y_1x_2y_2 \cdots x_ny_n) \subseteq \mathbb{R}^{2n}$
- $d_{\bar{G}} \subseteq \mathbb{R}^{|V_G|}$
- $\mathbb{R}^{2n} \setminus E_2$

Given (G, d) o/w d_G

$$\{(x_1y_1x_2y_2 \cdots x_ny_n) : (x_v - x_w)^2 + (y_v - y_w)^2 = d_{vw}^2 \forall (v, w) \in E(G) \setminus E_2\}$$

\leftrightarrow

$$d_{\bar{G}} = \{(x_a - x_b)^2 + (y_a - y_b)^2, \cdots (a, b) \notin E(G), : (x_v - x_w)^2 + (y_v - y_w)^2 = d_{vw}^2 \forall (v, w) \in E(G)\}$$

There is one to one map between these two sets.

Typical embedding: An embedding Q of G is generic if

\exists a small enough neighborhood of $(d_{Q,G})$, $d_{Q,G \pm \xi}$, all realization of $(G, d_{Q,G \pm \xi})$ are rigid $\Leftrightarrow Q$ is rigid.

Alternately, One can define a small enough neighborhood of Q itself, Require all corresponding realization to be rigid for their corresponding distance values.

3.3.1.3 Rigidity of Graph:

Def1: A Graph is rigid \exists a generic embedding that is rigid.

Def2: A Graph is rigid if all generic embeddings are rigid.

These two definitions turn out to be equivalent and we will give the proof in the following notes.

Def3: A Graph is globally rigid if it is rigid &

\forall generic embedding Q with distances $d_{G,Q}$, Q is the unique generic realization of $(G, d_{G,Q})$

Def4: An embedding Q of G is rigid if

\exists a small enough \mathbb{R}^{2n} - neighborhood Q_ξ , such that for $\forall Q' \in Q_\xi$, Q' is a realization of $(G, d_{Q,G}) \Leftrightarrow Q'$ is a rigid motion of Q .

Def5: An embedding Q of G is generic if

\exists a small enough \mathbb{R}^{2n} - neighborhood Q_ξ , such that $\forall Q' \in Q_\xi$, Q' is rigid $\Leftrightarrow Q$ is rigid.

Question: Given a particular embedding $Q \in \mathbb{R}^{2n}$ of G , Decide

1. is Q generic?
2. is Q rigid?

3.3.1.4 Laman's theorem Proof

Laman's-theorem Given graph $G = (V, E)$, G is generically rigid in $2[k]$ dimensions $\Leftrightarrow [\Rightarrow] \exists G' = (V, E'), E' \subseteq E$ such that

1. $\forall S \subseteq G', 2|V_S| - |E_S| \geq 3 \quad [k|V_S| - |E_S| \geq \binom{k+1}{2}]$
2. $2|V| - |E'| = 3 \quad [k|V| - |E'| = \binom{k+1}{2}]$

• \Rightarrow Proof:

Def: Rigidity Matrix $R_{P,G}$ of an embedding P in \mathbb{R}^k of a graph $G = (V, E)$ is

$$\begin{pmatrix} p_1 & p_2 & \underbrace{\quad}_k & p_i & p_{|V|} \\ e_1 & & & & \\ & \ddots & & & \\ \vdots & & & & \\ e_i & 0 & 0 & 0 & (p_i - p_j) & 0 \\ & & & & & \dots \end{pmatrix} \quad e_i = (v_i - v_j)$$

Fact1: Consider the vector $\begin{pmatrix} u_1 \\ \vdots \\ u_{|V|} \end{pmatrix} \quad u_i \in \mathbb{R}^k, \text{ s.t. } R_{P,G}U = 0$ it means
 $u_1 \cdots u_{|V|} \text{ s.t. } \forall i, j \ (v_i, v_j) \in E \quad \langle (p_i - p_j)(u_i - u_j) \rangle = 0$

The set of independent U's with this property is a basis for the tangent space of the variety $\forall (v_i, v_j) \in E \quad \|q_i - q_j\| - \|p_i - p_j\| = 0$ at the point $p \in \mathbb{R}^{k|V|}$

Fact2: row rank of $R_{P,G} = k|V| - \text{rank of } S_{P,G}$

Lemma1: P is generic then P is rigid $\Leftrightarrow R_{P,G}$ has rank $k|V| - \binom{k+1}{2}$

Proof:

\Leftarrow True, Full rank then rigid

\Rightarrow if $R_{P,G}$ has rank $< k|V| - \binom{k+1}{2}$ then if P is rigid $\Rightarrow P$ is not generic.

Lemma2: if P is generic embedding of $G = (V, E)$ & $R_{P,G}$ has $(k|v| - \binom{k+1}{2})$ rank then

Laman's theorem for general dimensions k must hold.

Laman's theorem \Rightarrow for general k dimensions follows from lemma1, lemma2 and definition of generic rigidity of G

• \Leftarrow Proof

Laman's theorem \Leftarrow only for 2 dimensions, starting from a graph $G = (V, E)$ for which the RHS holds, Laman showed

1. G has "Henneberg" construction
2. if G has a Henneberg construction, then it has a generic and rigid embedding.

Laman's theorem \Leftarrow : If a graph $G = (V, E)$ satisfies Laman condition, then \exists a generic rigid embedding $P \in \mathbb{R}^{2|V|}$ of G

Lemma1: If G satisfies Laman condition 1, then graph G has a Henneberg construction

Observation1: If graph G has a Henneberg construction, then the abstract underlying matroid underlying G is "1-extendible"

Lemma2: If G satisfies the Laman condition 1 and the abstract rigidity matroid underlying G is "1-extendible" then the edges in G are generically independent

Observation2: If G satisfies both Laman conditions, then G has a generic rigid embedding.

Matroid:

Def1: Matroid M : finite set (E, \mathcal{I}) , & $\mathcal{I} \subseteq \text{Power}(E)$ &

1. $\phi \in \mathcal{I}$

2. $S \in \mathcal{I}$ then $\forall Q \subseteq S, Q \in \mathcal{I}$

3. $S(\text{not maximal}) \in \mathcal{I}$, then $\exists u \notin S, \forall v \in S, \text{ s.t. } (S \setminus v \cup \{u\}) \in \mathcal{I}$

(3' If $S_1, S_2 \in \mathcal{I}$, $|S_1| < |S_2|$ then \exists an element $u \in S_2 \setminus S_1$, s.t $S_1 \cup \{u\} \in \mathcal{I}$)

Examples:

1. Let E be a set of vectors in \mathbb{R}^m or \mathcal{F}^m (any field), Let \mathcal{I} be the set of all linearly independent subset of E , claim (E, \mathcal{I}) is a matroid.
2. $G = (V, E)$, $M_G = (E, \mathcal{I})$, $\mathcal{I} = \{\text{any subset of edge that does not have a cycle}\}$
3. Fano plane $E = \{p_1 \cdots p_7\}$, $\mathcal{I} = \text{set of all subsets of points that are not collinear}$

Facts: All maximal¹ independent sets have the same number elements called $\text{rank}(M)$ in them

Def2: Matroid M : finite set E & a closure $\langle \rangle$: $\mathcal{P}ower(E) \rightarrow \mathcal{P}ower(E)$

1. $Q \subseteq \langle Q \rangle$
2. $\langle \langle Q \rangle \rangle = \langle Q \rangle$
3. If $Q_1 \subseteq Q_2$ then $\langle Q_1 \rangle \subseteq \langle Q_2 \rangle$
4. If $s, t \in E \setminus \langle T \rangle$ then $s \in \langle T \cup \{t\} \rangle \Leftrightarrow t \in \langle T \cup \{s\} \rangle$

Examples:

1. fano plane, $E = \{p_1 \cdots p_7\}$, $\langle p_1 \rangle = p_1$

for $k \geq 2$, if $p_1 \cdots p_7$ lie on a line, then $\langle p_1 \cdots p_7 \rangle$ are all points on this line

if $p_1 \cdots p_7$ donot lie on any line, then $\langle p_1 \cdots p_7 \rangle$ are all points

2. affine dependent matroid

$E = \{p_1 \cdots p_7\} \in \mathbb{R}^m$, $\langle p_1 \cdots p_7 \rangle = \text{all points in the affine span of } (p_1 \cdots p_7) \in E$

Def3: Infinitesimal complete rigidity matroid

Given $P = \{p_1 \cdots p_m\}$, $p_i \in \mathbb{R}^k$, **embedding of G**

$M = (E, \mathcal{I})$ $\mathcal{I} = \text{set of all linearly independent subsets of rows of the complete rigidity matrix}$

¹ An independent set to which no elements can be added & maintain independent

E =rows of the complete rigidity matrix

Def4: Generic k -dimension rigidity matroid of a graph $G = (V, E)$ $\mathcal{G}_k = (E, \mathcal{I})$, \mathcal{I} is obtained as follows:

take any generic embedding P of G in k -dimension & define \mathcal{I} to be the same as for the infinitesimal rigidity matroid for P_G

Def5: Abstract rigidity matroid on a complete graph of a vertex set V

E =set of all possible edges of V

The closure operator satisfies all matroid conditions and the following condition:

5. if $Q_1, Q_2 \subseteq E$, & $|V(Q_1) \cap V(Q_2)| < k$, then $\langle Q_1 \cup Q_2 \rangle \subseteq \text{Completion}(V(Q_1)) \cup \text{Completion}(V(Q_2))$

Def6: If $Q_1, Q_2 \subseteq E$ are abstract rigid², and $|V(Q_1) \cap V(Q_2)| \geq k$, then $\langle Q_1 \cup Q_2 \rangle$ is rigid

3.3.2 Jackson-Jordon theorem

for $d = 2$, $G = (V, E)$ generically has an unique solution (globally rigid)
 $\Leftrightarrow G$ is redundantly rigid & 3-connected or it is a triangle.

Redundantly rigid: removal of any edge preserves rigidity of G .

3.3.2.1 Hendrickson's theorem

$G = (V, E)$ is globally rigid in d dimension $\Leftrightarrow G$ is reduntantly rigid for d dimension & $(d + 1)$ connected.

\Leftarrow proved

\Rightarrow Conely disproved for $d \geq 3$

\Rightarrow proved (Jackson-Jordon theorem)

² Q is abstract rigid if $\langle Q \rangle = \text{Completion}(V(Q))$

3.3.3 Owen's theorem

A graph is quadratically solvable \Leftrightarrow it is not 3-connected.

Quadratically solving: A constraint system (G, d) is quadratically solvable if it is triangularizable into quadratics.

\Leftarrow proved

\Rightarrow For planar graph, a graph is quadratically solvable \Rightarrow it is not 3-connected

\Rightarrow For general graph, open problem