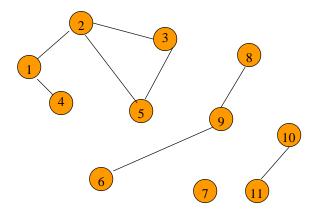
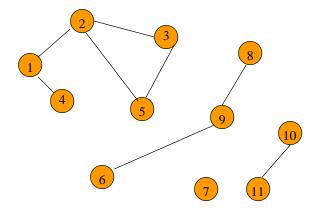
### **Graph Search Methods**

• A vertex **u** is reachable from vertex **v** iff there is a path from **v** to **u**.



### **Graph Search Methods**

A search method starts at a given vertex v and visits/labels/marks every vertex that is reachable from v.

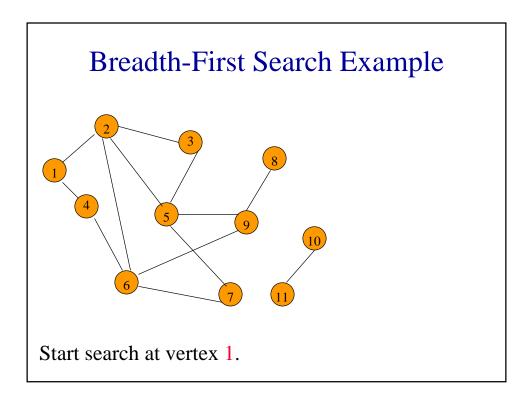


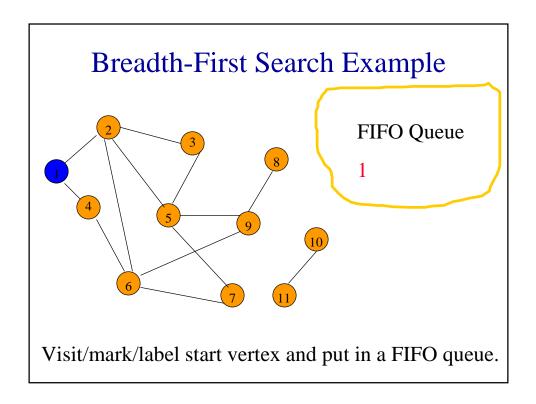
### **Graph Search Methods**

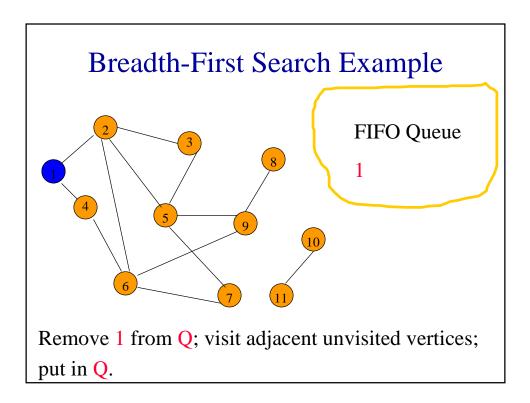
- Many graph problems solved using a search method.
  - Path from one vertex to another.
  - Is the graph connected?
  - Find a spanning tree.
  - Etc.
- Commonly used search methods:
  - Breadth-first search.
  - Depth-first search.

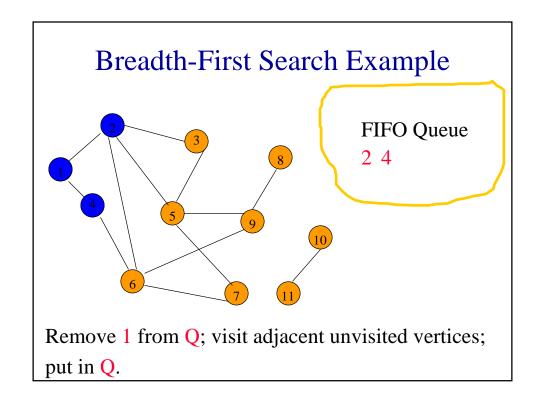
### Breadth-First Search

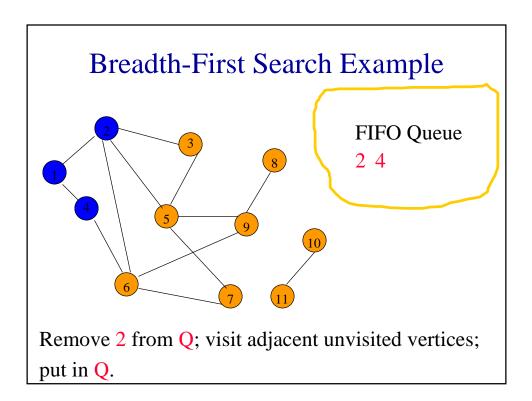
- Visit start vertex and put into a FIFO queue.
- Repeatedly remove a vertex from the queue, visit its unvisited adjacent vertices, put newly visited vertices into the queue.

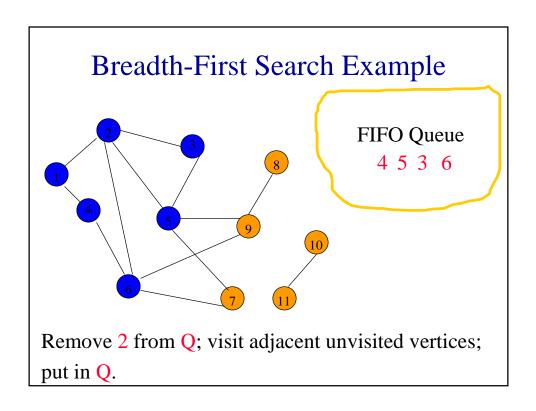


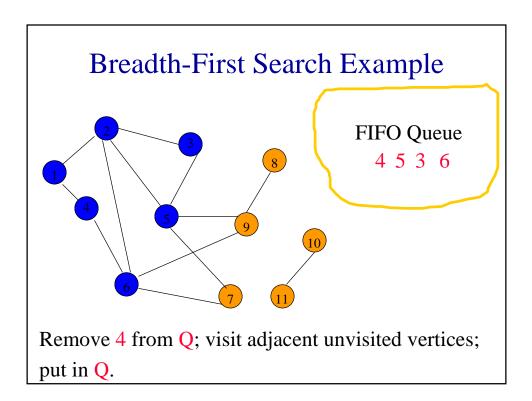


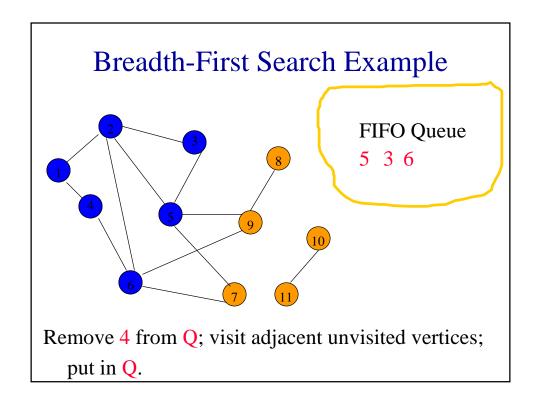


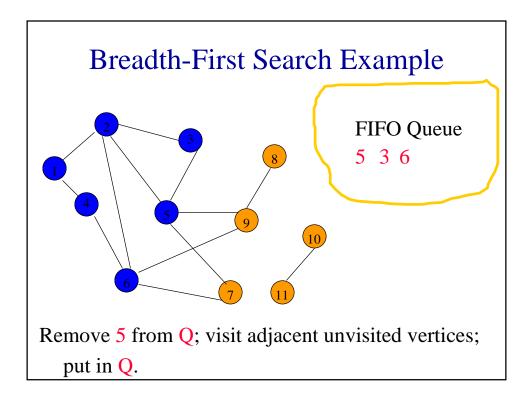


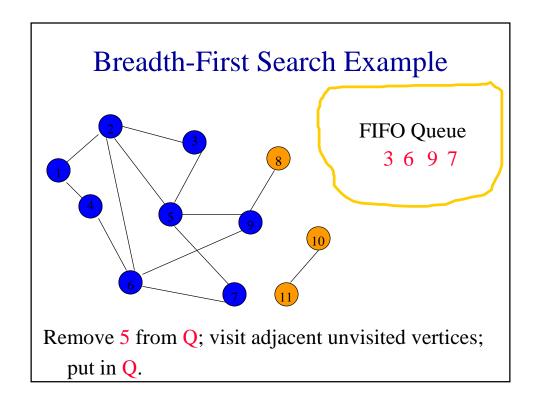


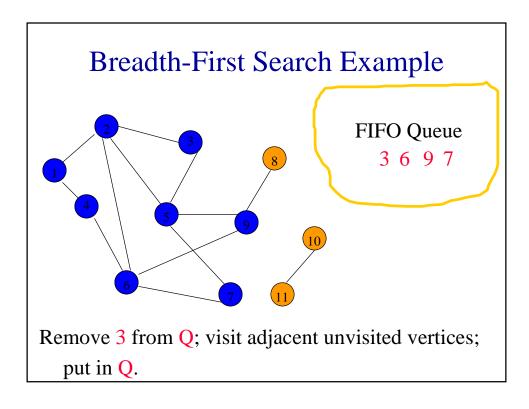


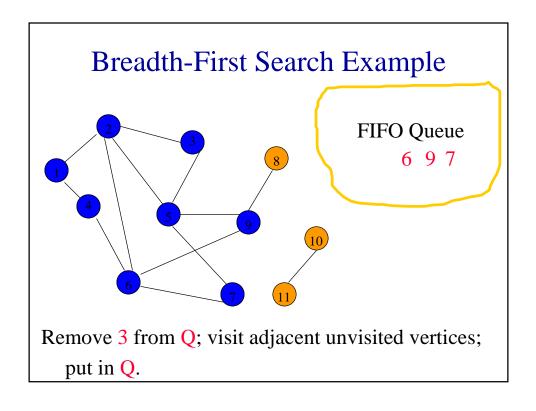


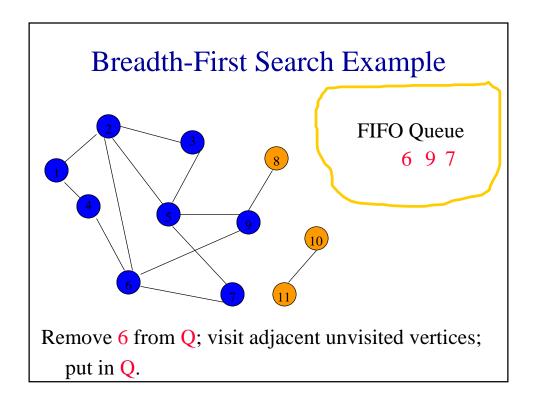


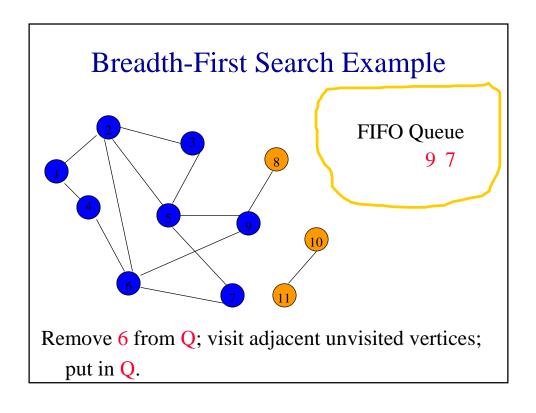


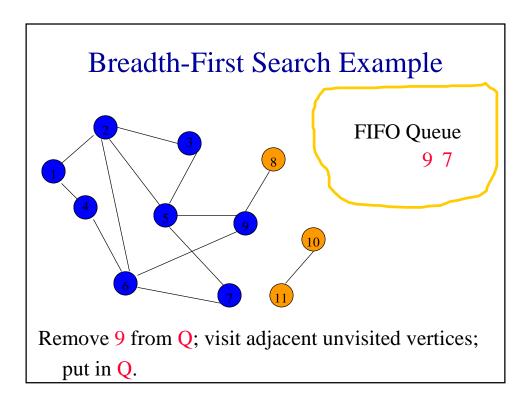


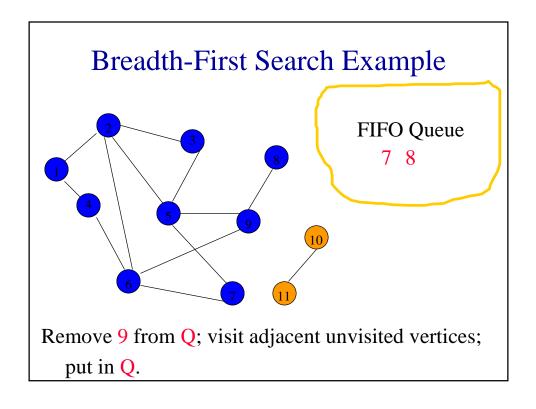


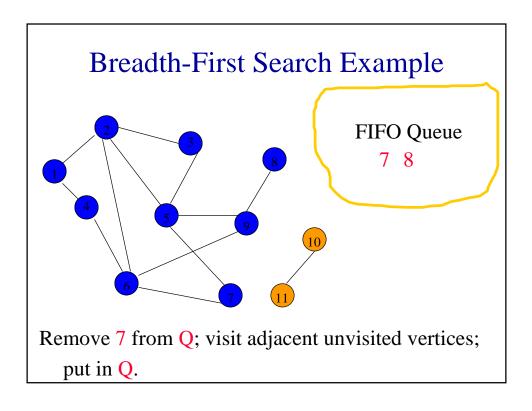


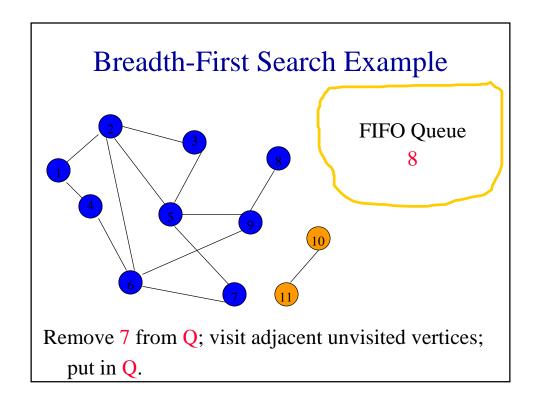


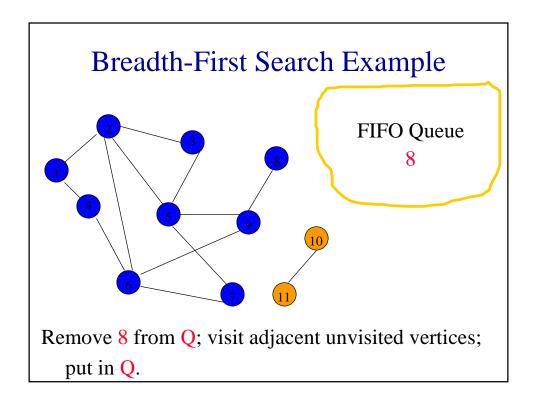


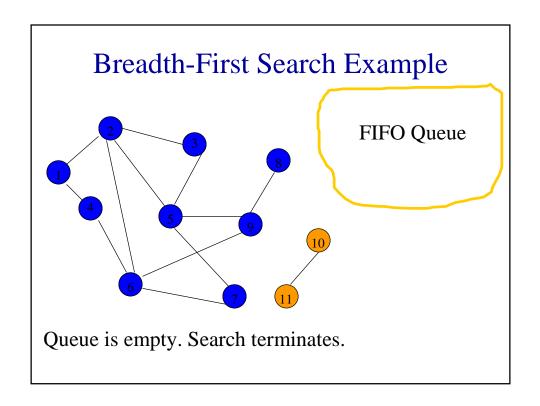












### **Breadth-First Search Property**

• All vertices reachable from the start vertex (including the start vertex) are visited.

### Time Complexity



- Each visited vertex is put on (and so removed from) the queue exactly once.
- When a vertex is removed from the queue, we examine its adjacent vertices.
  - O(n) if adjacency matrix used
  - O(vertex degree) if adjacency lists used
- Total time
  - O(mn), where m is number of vertices in the component that is searched (adjacency matrix)

### Time Complexity



- O(n + sum of component vertex degrees) (adj. lists)
  - = O(n + number of edges in component)

### Path From Vertex v To Vertex u

- Start a breadth-first search at vertex v.
- Terminate when vertex u is visited or when
   Q becomes empty (whichever occurs first).
- Time
  - O(n²) when adjacency matrix used
  - O(n+e) when adjacency lists used (e is number of edges)

### Is The Graph Connected?

- Start a breadth-first search at any vertex of the graph.
- Graph is connected iff all n vertices get visited.
- Time
  - O(n²) when adjacency matrix used
  - O(n+e) when adjacency lists used (e is number of edges)

### **Connected Components**

- Start a breadth-first search at any as yet unvisited vertex of the graph.
- Newly visited vertices (plus edges between them) define a component.
- Repeat until all vertices are visited.

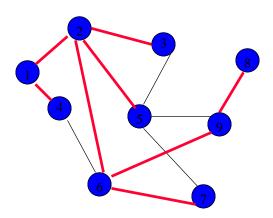
# 

## Time Complexity



- O(n²) when adjacency matrix used
- O(n+e) when adjacency lists used (e is number of edges)

### **Spanning Tree**



Breadth-first search from vertex 1.

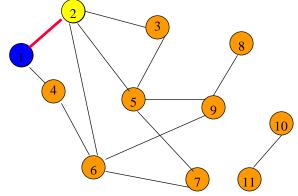
Breadth-first spanning tree.

### **Spanning Tree**

- Start a breadth-first search at any vertex of the graph.
- If graph is connected, the n-1 edges used to get to unvisited vertices define a spanning tree (breadth-first spanning tree).
- Time
  - O(n²) when adjacency matrix used
  - O(n+e) when adjacency lists used (e is number of edges)

### Depth-First Search

### Depth-First Search Example

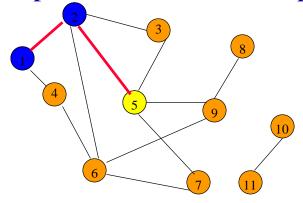


Start search at vertex 1.

Label vertex 1 and do a depth first search from either 2 or 4.

Suppose that vertex 2 is selected.

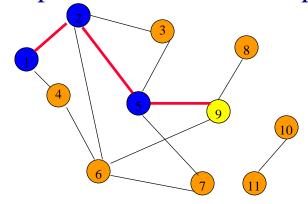
### Depth-First Search Example



Label vertex 2 and do a depth first search from either 3, 5, or 6.

Suppose that vertex 5 is selected.

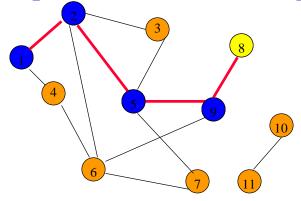
### Depth-First Search Example



Label vertex 5 and do a depth first search from either 3, 7, or 9.

Suppose that vertex 9 is selected.

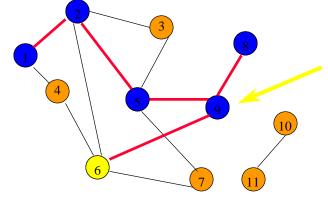
### Depth-First Search Example



Label vertex 9 and do a depth first search from either 6 or 8.

Suppose that vertex 8 is selected.

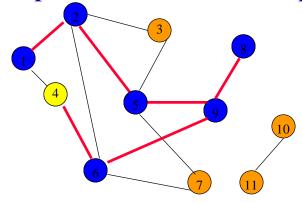
### Depth-First Search Example



Label vertex 8 and return to vertex 9.

From vertex 9 do a dfs(6).

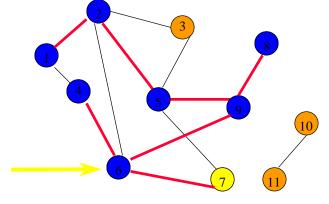
### Depth-First Search Example



Label vertex 6 and do a depth first search from either 4 or 7.

Suppose that vertex 4 is selected.

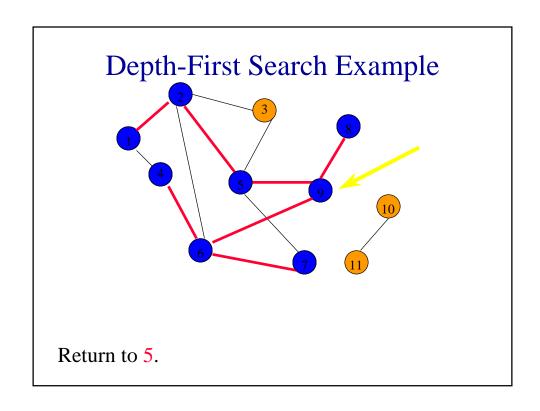
### Depth-First Search Example

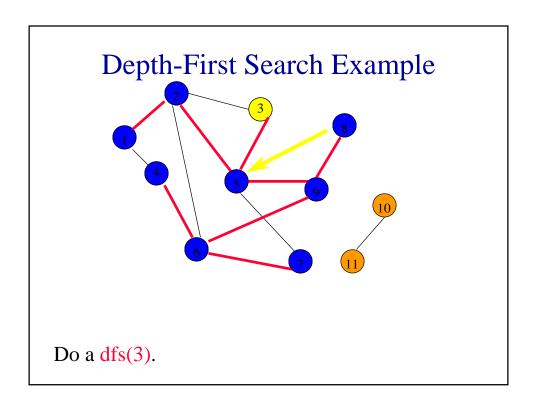


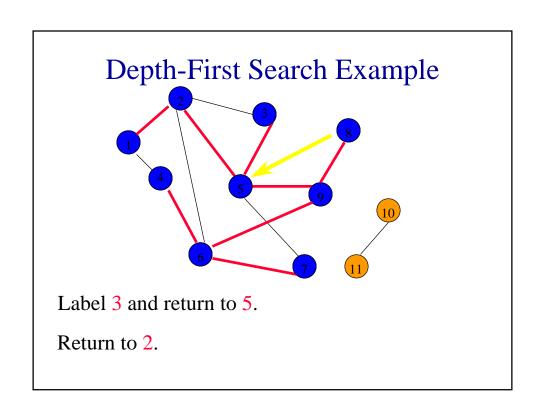
Label vertex 4 and return to 6.

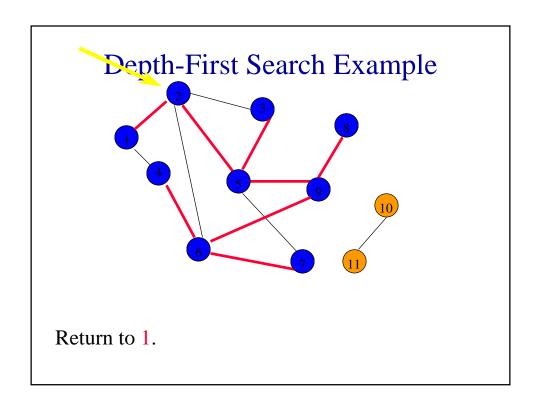
From vertex 6 do a dfs(7).

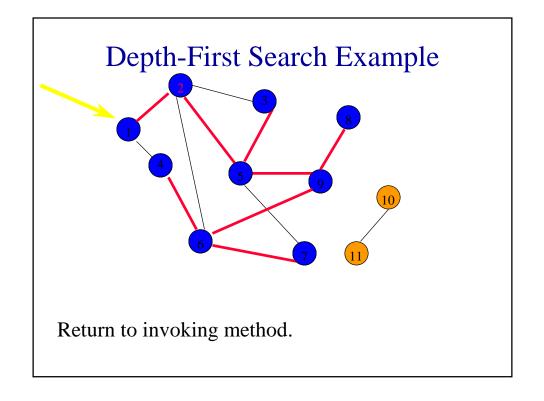
## Depth-First Search Example 3 8 Label vertex 7 and return to 6. Return to 9.











### **Depth-First Search Properties**

- Same complexity as BFS.
- Same properties with respect to path finding, connected components, and spanning trees.
- Edges used to reach unlabeled vertices define a depth-first spanning tree when the graph is connected.
- There are problems for which bfs is better than dfs and vice versa.