

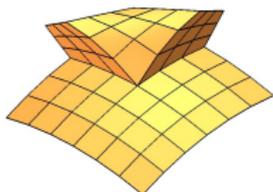
Multi-sided completion of C^2 bi-3 and C^1 bi-2 splines: A unifying approach

Kęstutis Karčiauskas

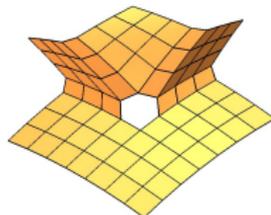
Vilnius University

Jörg Peters

University of Florida



irregular point



irregular face

NIH, Darpa

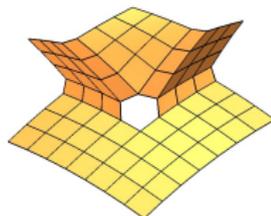
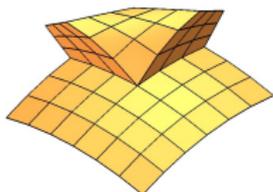
Multi-sided completion of C^2 bi-3 and C^1 bi-2 splines: A unifying approach

Kęstutis Karčiauskas

Vilnius University

Jörg Peters

University of Florida



Quad mesh = spline control net?

NIH, Darpa

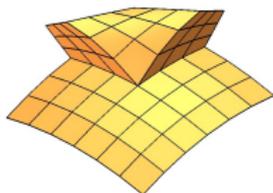
Multi-sided completion of C^2 bi-3 and C^1 bi-2 splines: A unifying approach

Kęstutis Karčiauskas

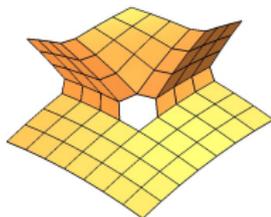
Vilnius University

Jörg Peters

University of Florida



Catmull-Clark:
recursion
poor shape



Quad mesh = spline control net?

NIH, Darpa

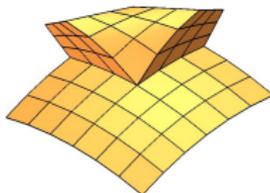
Multi-sided completion of C^2 bi-3 and C^1 bi-2 splines: A unifying approach

Kęstutis Karčiauskas

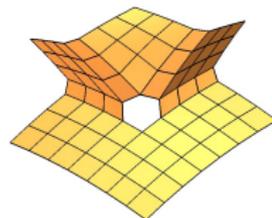
Vilnius University

Jörg Peters

University of Florida



Catmull-Clark:
recursion
poor shape



Doo-Sabin:
recursion
worse shape

NIH, Darpa

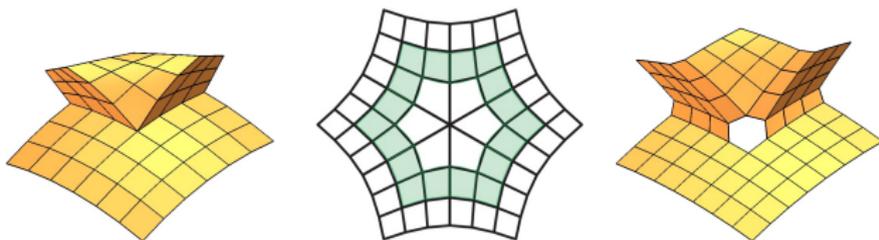
Multi-sided completion of C^2 bi-3 and C^1 bi-2 splines: A unifying approach

Kęstutis Karčiauskas

Vilnius University

Jörg Peters

University of Florida

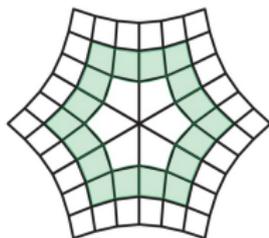
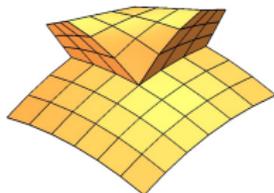


C^2 bi-3
NIH, Darpa

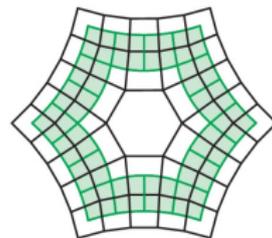
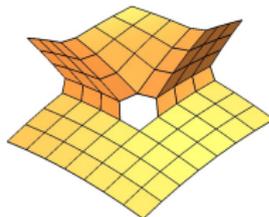
Multi-sided completion of C^2 bi-3 and C^1 bi-2 splines: A unifying approach

Kęstutis Karčiauskas
Vilnius University

Jörg Peters
University of Florida



C^2 bi-3
NIH, Darpa



C^1 bi-2

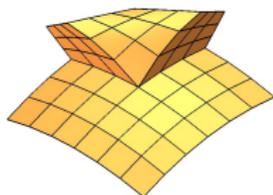
Multi-sided completion of C^2 bi-3 and C^1 bi-2 splines: A unifying approach

Kęstutis Karčiauskas

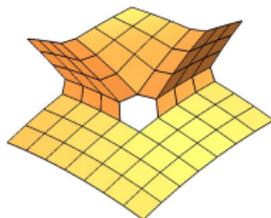
Vilnius University

Jörg Peters

University of Florida



C^2 bi-3



C^1 bi-2



NIH, Darpa

Idea: transition layer + unified cap



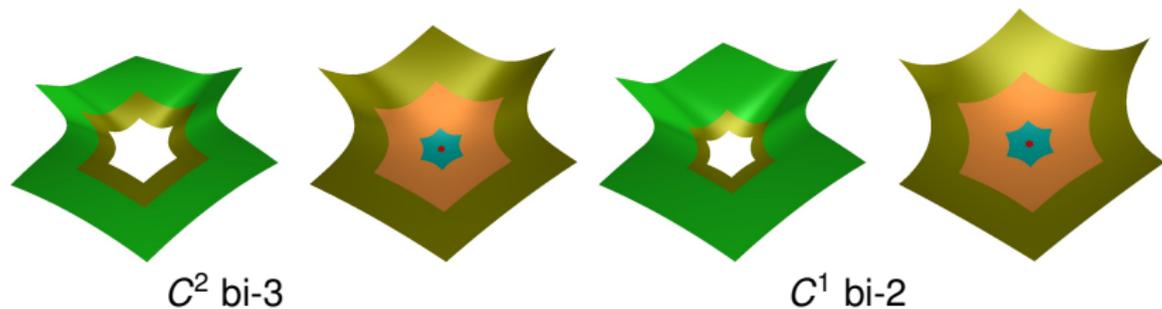
C^2 bi-3



C^1 bi-2

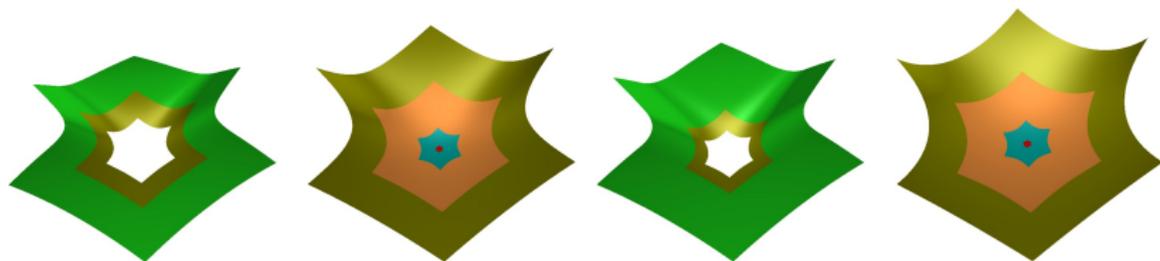
fill challenge: good shape, refinability

Idea: transition layer + unified cap



fill challenge: good shape, refinability

Idea: transition layer + unified cap



C^2 bi-3

C^1 bi-2

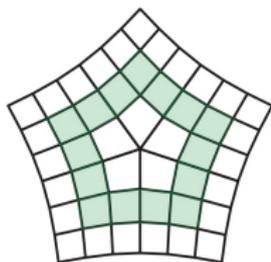


interrogation: highlight lines
fill challenge: good shape, refinability

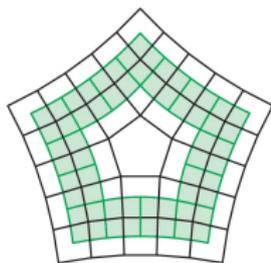
Outline

- 1 Transition Ring + Tensor-border
- 2 Unified (hybrid) cap = bi-4 rings + tiny cap
- 3 Examples & Comparison

Net & tensor-border

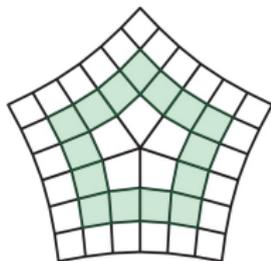


bi-3 ring

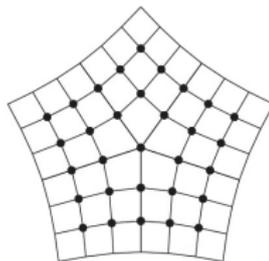


bi-2 ring

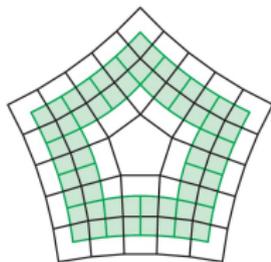
Net & tensor-border



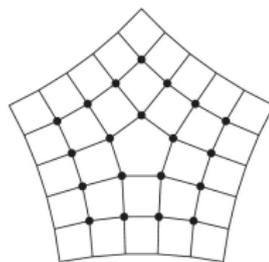
bi-3 ring



● : CC-net

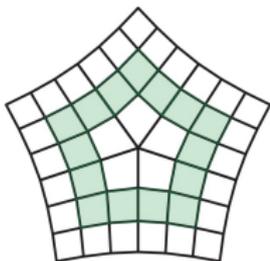


bi-2 ring

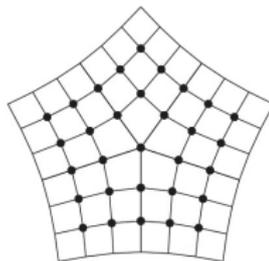


● : DS-net

Net & tensor-border



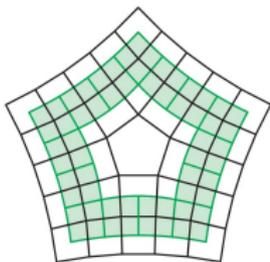
bi-3 ring



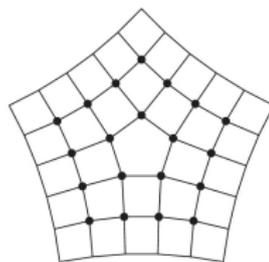
• : CC-net



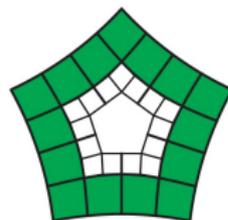
bi-3 ring + tensor-border



bi-2 ring

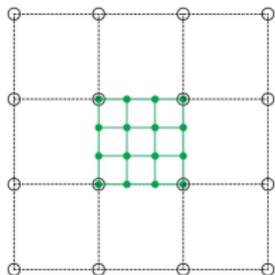


• : DS-net

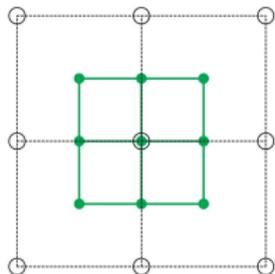


bi-2 ring + tensor-border

B-spline and BB-form (Bernstein-Bézier)

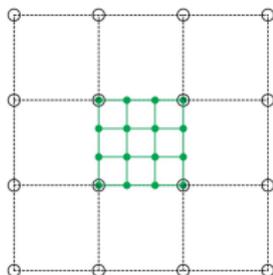


C^2 bi-3

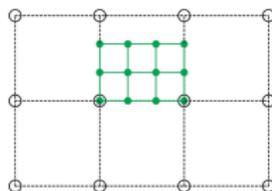


C^1 bi-2

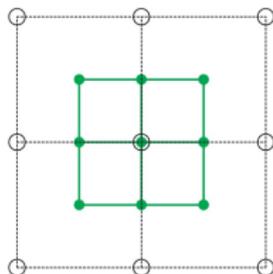
B-spline and BB-form (Bernstein-Bézier)



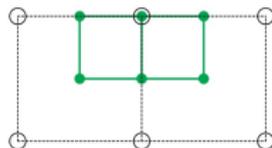
C^2 bi-3



tensor-border

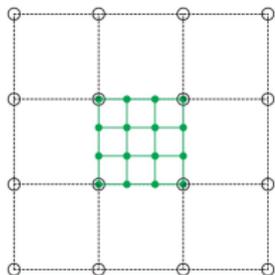


C^1 bi-2

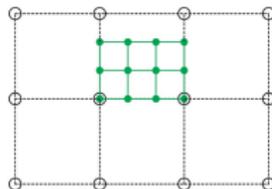


tensor-border

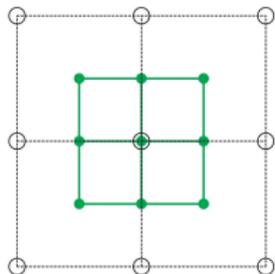
B-spline and BB-form (Bernstein-Bézier)



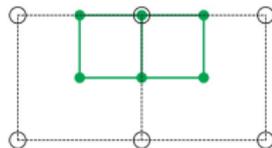
C^2 bi-3



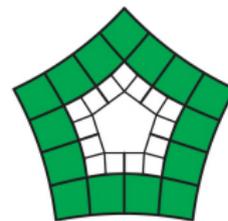
tensor-border



C^1 bi-2

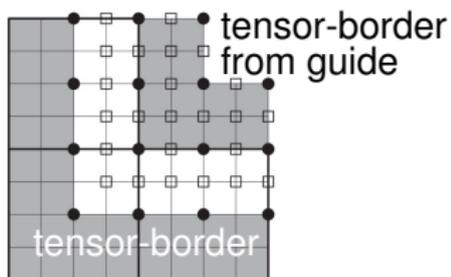


tensor-border



Contracting bi-4 rings

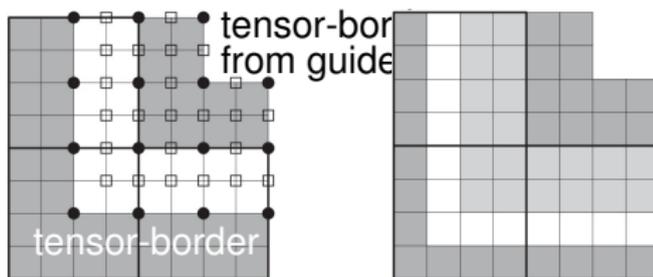
bi-4 sector



transition: from bi-3

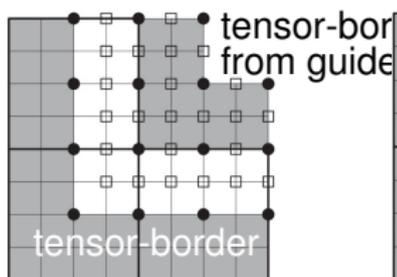
Contracting bi-4 rings

bi-4 sector

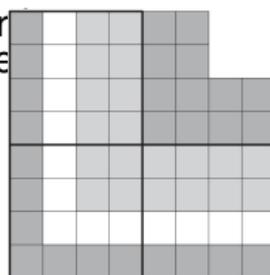


Contracting bi-4 rings

bi-4 sector

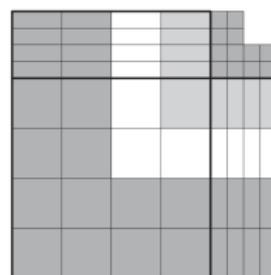


transition: from bi-3



from bi-2

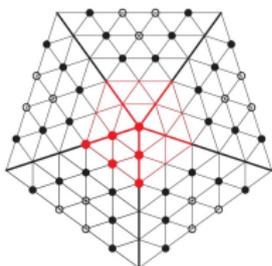
rapid contraction



main body

Good shape from a Guide Surface

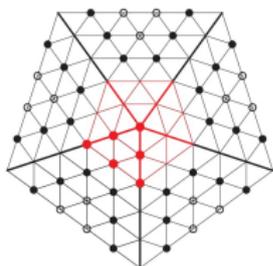
C^1 guide \mathbf{g} (degree 5) computed by *linear operator* from CC-net or DS-net



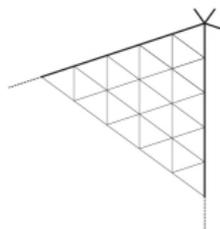
g

Good shape from a Guide Surface

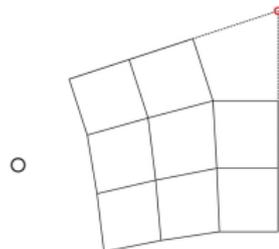
C^1 guide \mathbf{g} (degree 5) computed by *linear operator* from CC-net or DS-net



\mathbf{g}



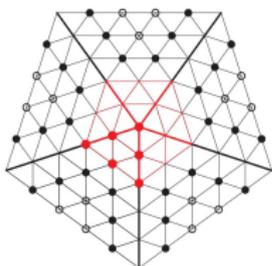
sector of \mathbf{g}



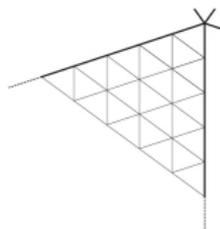
χ_σ

Good shape from a Guide Surface

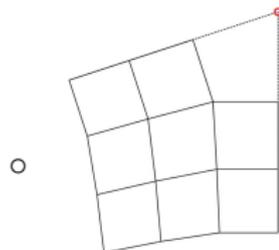
C^1 guide \mathbf{g} (degree 5) computed by *linear operator* from CC-net or DS-net



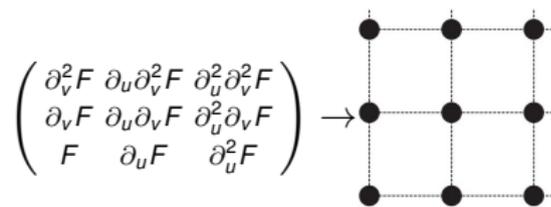
\mathbf{g}



sector of \mathbf{g}



$\chi\sigma$

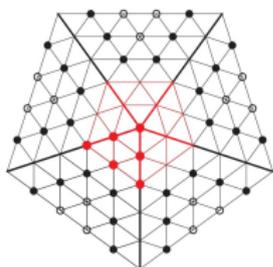


$$\begin{pmatrix} \partial_v^2 F & \partial_u \partial_v^2 F & \partial_u^2 \partial_v^2 F \\ \partial_v F & \partial_u \partial_v F & \partial_u^2 \partial_v F \\ F & \partial_u F & \partial_u^2 F \end{pmatrix} \rightarrow$$

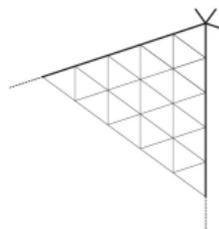
Hermite data (derivatives) \rightarrow to BB-form

Good shape from a Guide Surface

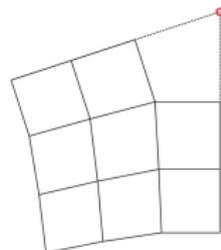
C^1 guide \mathbf{g} (degree 5) computed by *linear operator* from CC-net or DS-net



\mathbf{g}

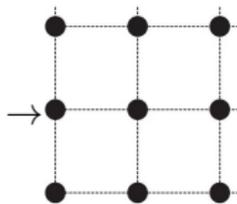


sector of \mathbf{g}

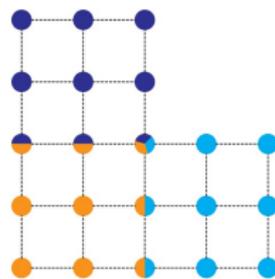


χ_σ

$$\begin{pmatrix} \partial_v^2 F & \partial_u \partial_v^2 F & \partial_u^2 \partial_v^2 F \\ \partial_v F & \partial_u \partial_v F & \partial_u^2 \partial_v F \\ F & \partial_u F & \partial_u^2 F \end{pmatrix} \rightarrow$$

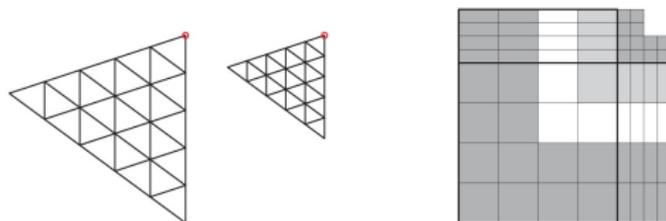
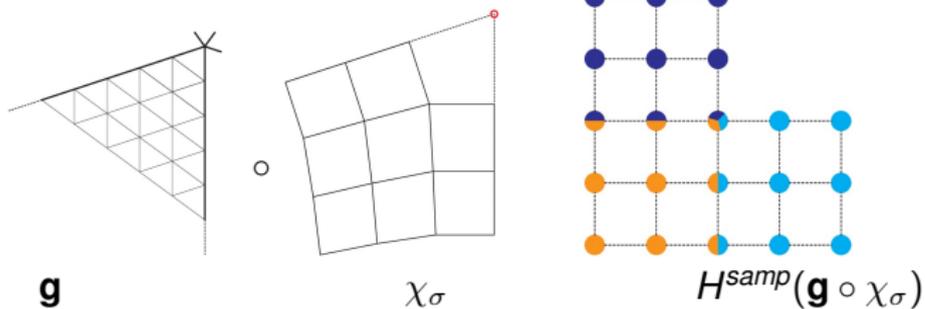


Hermite data (derivatives) \rightarrow to BB-form



L-shaped bi-4 tensor-border

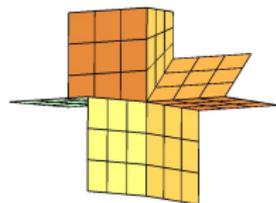
Good shape from a Guide Surface



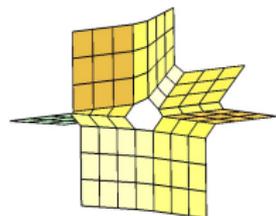
recursion via domain scaling

- 1 Transition Ring + Tensor-border
- 2 Unified (hybrid) cap = bi-4 rings + tiny cap
- 3 Examples & Comparison**

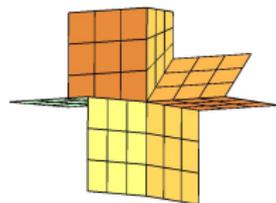
Surfaces from quad meshes ($n = 7$)



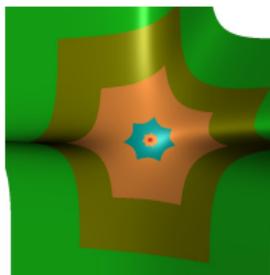
extended CC-net



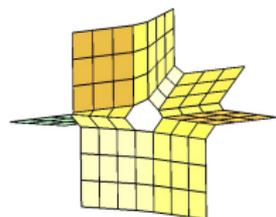
extended DS-net

Surfaces from quad meshes ($n = 7$)

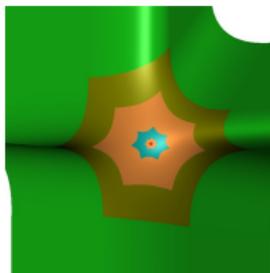
extended CC-net



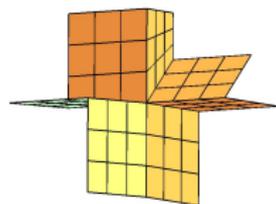
layout



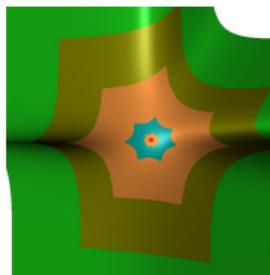
extended DS-net



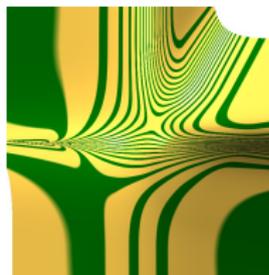
layout

Surfaces from quad meshes ($n = 7$)

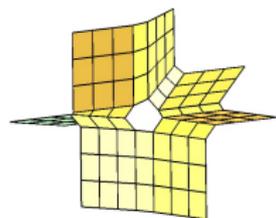
extended CC-net



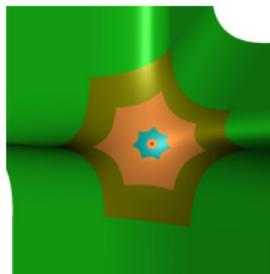
layout



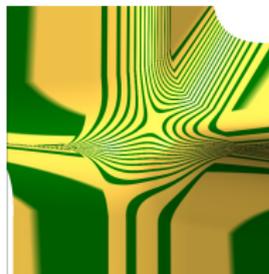
bi-3 + unified



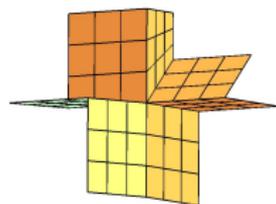
extended DS-net



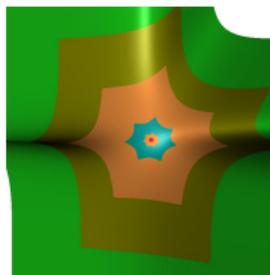
layout



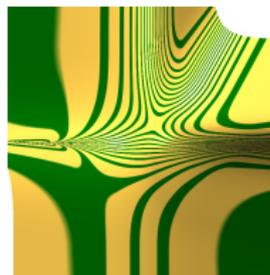
bi-2 + unified

Surfaces from quad meshes ($n = 7$)

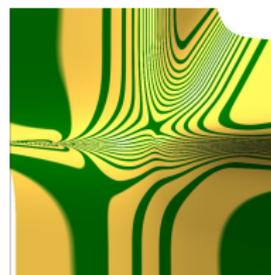
extended CC-net



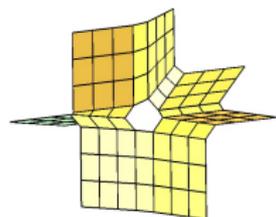
layout



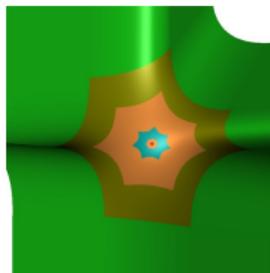
bi-3 + unified



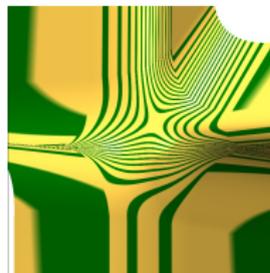
Catmull-Clark



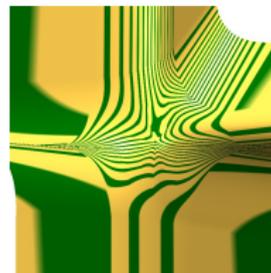
extended DS-net



layout



bi-2 + unified

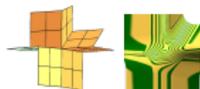


Doo-Sabin

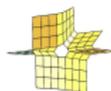
Summary

- One algorithm for capping both CC-nets (bi-3) and DS-net (bi-2).
- Parameterically C^1 or C^2 joined rings (except for G^1 tiny cap).
- Bi-4 rings are refinable, converge rapidly

- Can interpret CC-net as bi-2 + cap control net (see paper)



- Can also interpret DS-net as bi-3 + cap control net (not in paper: requires more machinery to obtain good shape)

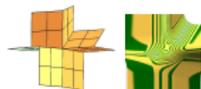


- **Questions?**

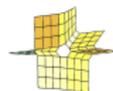
Summary

- One algorithm for capping both CC-nets (bi-3) and DS-net (bi-2).
- Parameterically C^1 or C^2 joined rings (except for G^1 tiny cap).
- Bi-4 rings are refinable, converge rapidly

- Can interpret CC-net as bi-2 + cap control net (see paper)



- Can also interpret DS-net as bi-3 + cap control net (not in paper: requires more machinery to obtain good shape)

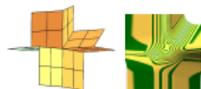


- **Questions?**

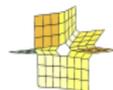
Summary

- One algorithm for capping both CC-nets (bi-3) and DS-net (bi-2).
- Parameterically C^1 or C^2 joined rings (except for G^1 tiny cap).
- Bi-4 rings are refinable, converge rapidly

- Can interpret CC-net as bi-2 + cap control net (see paper)



- Can also interpret DS-net as bi-3 + cap control net (not in paper: requires more machinery to obtain good shape)

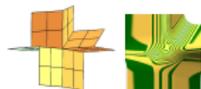


- **Questions?**

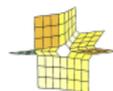
Summary

- One algorithm for capping both CC-nets (bi-3) and DS-net (bi-2).
- Parameterically C^1 or C^2 joined rings (except for G^1 tiny cap).
- Bi-4 rings are refinable, converge rapidly

- Can interpret CC-net as bi-2 + cap control net (see paper)



- Can also interpret DS-net as bi-3 + cap control net (not in paper: requires more machinery to obtain good shape)

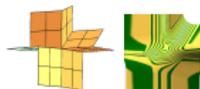


- **Questions?**

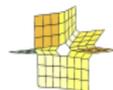
Summary

- One algorithm for capping both CC-nets (bi-3) and DS-net (bi-2).
- Parameterically C^1 or C^2 joined rings (except for G^1 tiny cap).
- Bi-4 rings are refinable, converge rapidly

- Can interpret CC-net as bi-2 + cap control net (see paper)



- Can also interpret DS-net as bi-3 + cap control net
(not in paper: requires more machinery to obtain good shape)

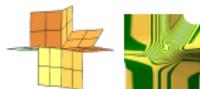


- Questions?

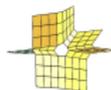
Summary

- One algorithm for capping both CC-nets (bi-3) and DS-net (bi-2).
- Parameterically C^1 or C^2 joined rings (except for G^1 tiny cap).
- Bi-4 rings are refinable, converge rapidly

- Can interpret CC-net as bi-2 + cap control net (see paper)



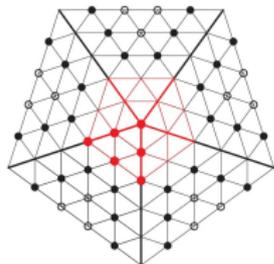
- Can also interpret DS-net as bi-3 + cap control net
(not in paper: requires more machinery to obtain good shape)



- **Questions?**

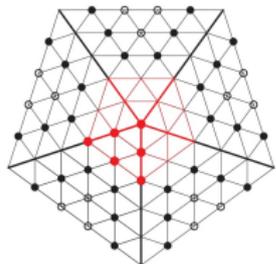
Blank

Good shape via a guide surface: computed by linear operator from CC-net or DS-net

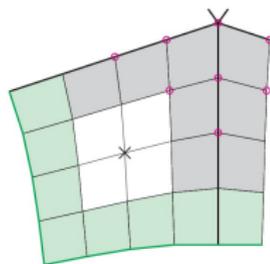


C^1 guide \mathbf{g} (degree 5)

Good shape via a guide surface: computed by linear operator from CC-net or DS-net

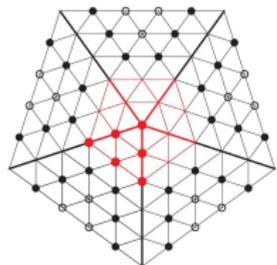


C^1 guide \mathbf{g} (degree 5)

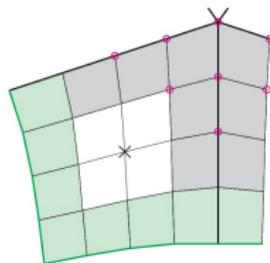


auxiliary G^1 bi-4 guide \mathbf{h}

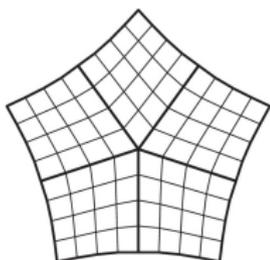
Good shape via a guide surface: computed by linear operator from CC-net or DS-net



C^1 guide \mathbf{g} (degree 5)

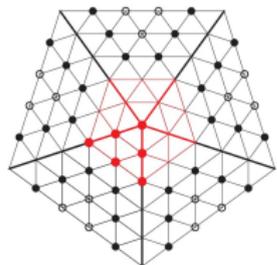


auxiliary G^1 bi-4 guide \mathbf{h}

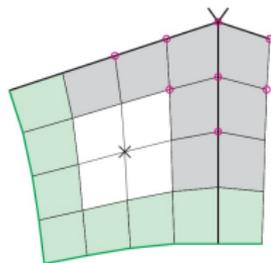


parameterization \mathbf{h}^{char}

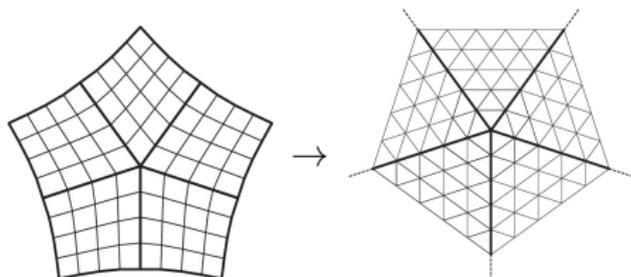
Good shape via a guide surface: computed by linear operator from CC-net or DS-net



C^1 guide \mathbf{g} (degree 5)



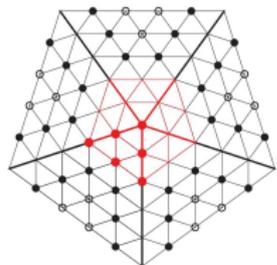
auxiliary G^1 bi-4 guide \mathbf{h}



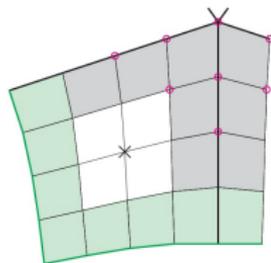
parameterization \mathbf{h}^{char}

\mathbf{g} , $9n + 5$ dofs

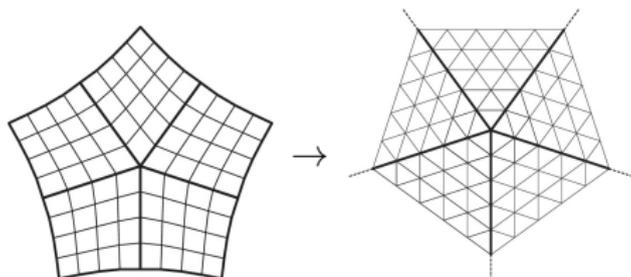
Good shape via a guide surface: computed by linear operator from CC-net or DS-net



C^1 guide \mathbf{g} (degree 5)

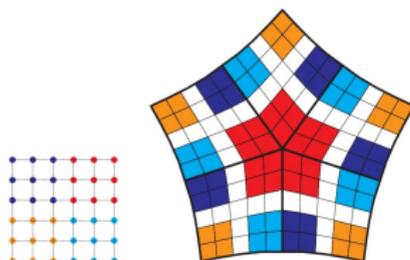


auxiliary G^1 bi-4 guide \mathbf{h}



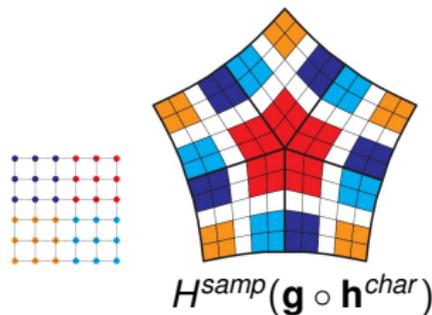
parameterization \mathbf{h}^{char}

\mathbf{g} , $9n + 5$ dofs

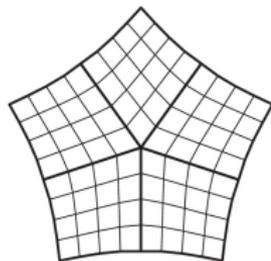


$H^{samp}(\mathbf{g} \circ \mathbf{h}^{char})$

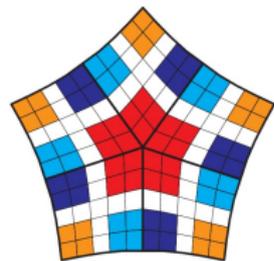
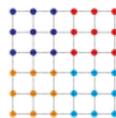
Good shape via a guide surface: computed by *linear operator* from CC-net or DS-net



Good shape via a guide surface: computed by *linear operator* from CC-net or DS-net

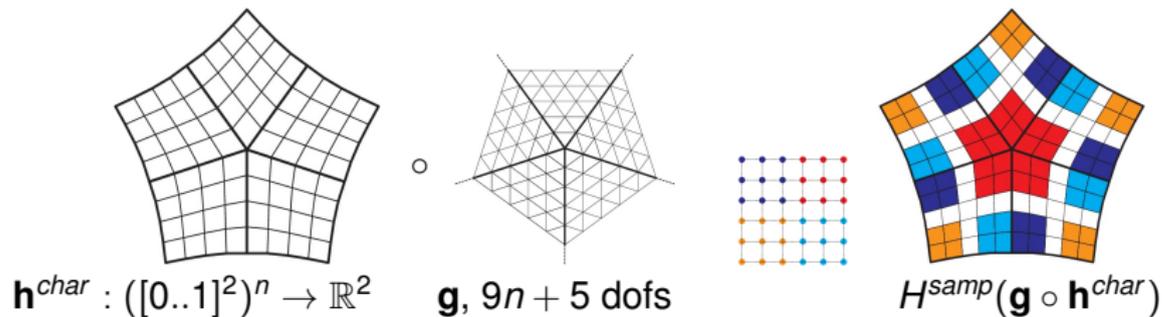


$$\mathbf{h}^{char} : ([0..1]^2)^n \rightarrow \mathbb{R}^2$$



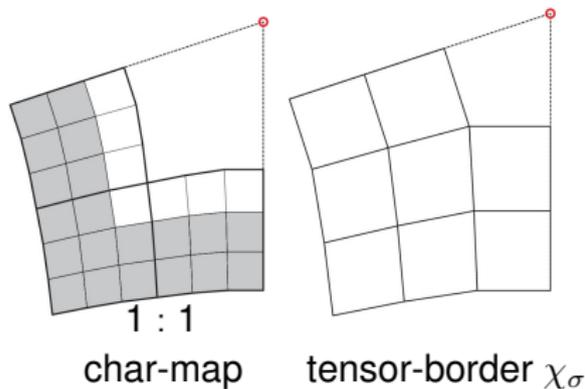
$$H^{samp}(\mathbf{g} \circ \mathbf{h}^{char})$$

Good shape via a guide surface: computed by *linear operator* from CC-net or DS-net



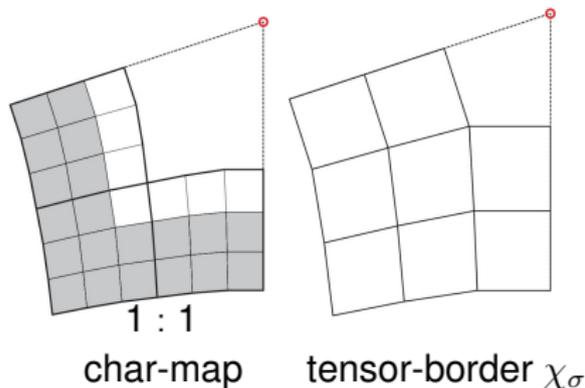
Parameterizations: characteristic maps and tensor-borders

Catmull-Clark subdivision ($\sigma := \frac{1}{2}$)

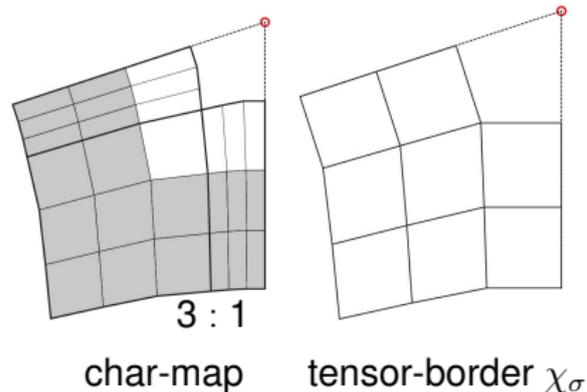


Parameterizations: characteristic maps and tensor-borders

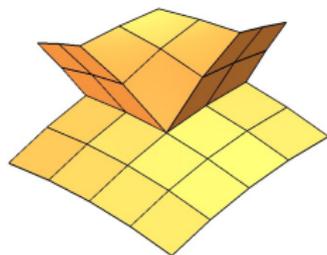
Catmull-Clark subdivision ($\sigma := \frac{1}{2}$)



adjustable speed subdivision ($\sigma := \frac{3}{4}$)

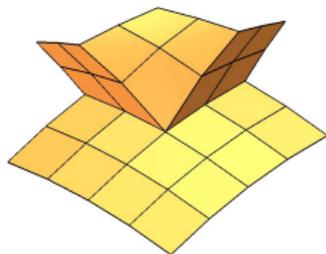


Quad-net \Rightarrow DS-net

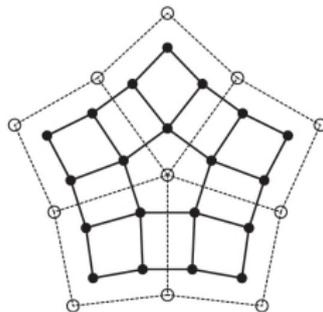


quad-net

Quad-net \Rightarrow DS-net

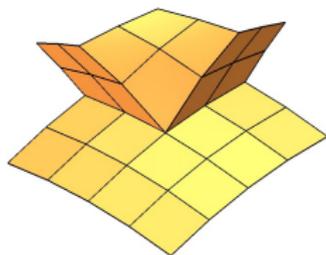


quad-net

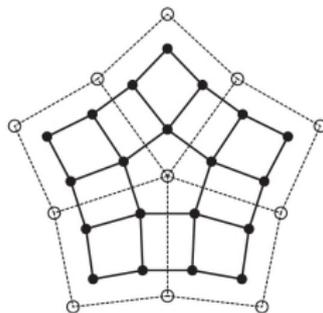


regular refinement

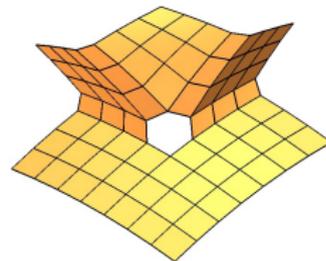
Quad-net \Rightarrow DS-net



quad-net



regular refinement



DS-net