

Self-Test cap{4,6}930: Geometric Modeling

Name:

If you need to make simple, reasonable assumptions to arrive at an answer, state any such assumption.

An answer 'yes' or 'no' is worth 0 points if it does not explain the reasoning.

Take this test twice.

- In red give answers without google and co.
- In black give answers after using any source (specify).

1 Coordinates

Consider the barycentric combination

$$\mathbf{b} := \sum_{j=0}^2 \alpha_j \mathbf{b}_j, \quad (\alpha_j) := \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right), \quad (\mathbf{b}_j) := \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \end{bmatrix}\right). \quad (1)$$

- Draw the barycentric combination as the sum of a point and two vectors.
- Draw the convex hull of the three points

2 Affine Maps

- Construct a matrix that maps $(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix})$ to $(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix})$.
- Prove that an affine map leaves barycentric combinations invariant.
- Determine an affine map that maps the points of Eq. (1) to the unit triangle $(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix})$
- What (roughly) is the shear map for generating the slanted "r" in Fig 2.4 of the book?

3 Functions

Consider the functions

$$b_i : \mathbb{R} \rightarrow \mathbb{R}, \quad b_i(t) := \binom{3}{i} (1-t)^{3-i} t^i, \quad i = 0, \dots, 3, \quad (2)$$

$$\text{where } \binom{n}{i} := \frac{n!}{(n-i)!i!} \text{ and } n! := n \cdot \dots \cdot 2 \cdot 1.$$

- Prove that the functions b_i are polynomials.
- Prove that the polynomials b_i are linearly independent.

4 Bonus

A ratio-preserving map leaves the ratio of three collinear points constant.
Prove: every ratio-preserving map is affine.