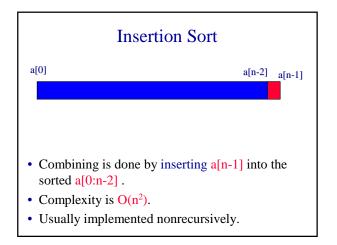


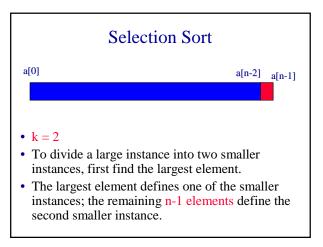
- Small instance.
  - $n \le 1$  elements.
  - $n \le 10$  elements.
  - We'll use n <= 1 for now.
- Large instance.
  - Divide into k >= 2 smaller instances.
  - k = 2, 3, 4, ... ?
  - What does each smaller instance look like?
  - Sort smaller instances recursively.
  - How do you combine the sorted smaller instances?

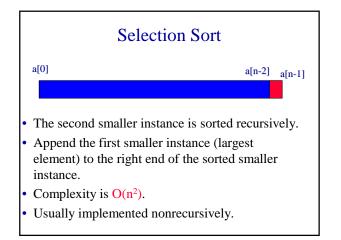


# a[0] a[n-2] a[n-1] k = 2 First n - 1 elements (a[0:n-2]) define one of the smaller instances; last element (a[n-1]) defines the second smaller instance.

- a[0:n-2] is sorted recursively.
- a[n-1] is a small instance.







## **Bubble Sort**

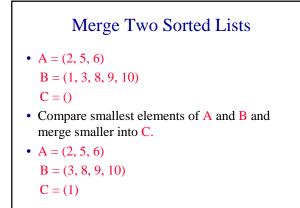
- Bubble sort may also be viewed as a k = 2 divideand-conquer sorting method.
- Insertion sort, selection sort and bubble sort divide a large instance into one smaller instance of size n - 1 and another one of size 1.
- All three sort methods take  $O(n^2)$  time.

# Divide And Conquer

- Divide-and-conquer algorithms generally have best complexity when a large instance is divided into smaller instances of approximately the same size.
- When k = 2 and n = 24, divide into two smaller instances of size 12 each.
- When k = 2 and n = 25, divide into two smaller instances of size 13 and 12, respectively.

## Merge Sort

- k = 2
- First ceil(n/2) elements define one of the smaller instances; remaining floor(n/2) elements define the second smaller instance.
- Each of the two smaller instances is sorted recursively.
- The sorted smaller instances are combined using a process called merge.
- Complexity is O(n log n).
- Usually implemented nonrecursively.

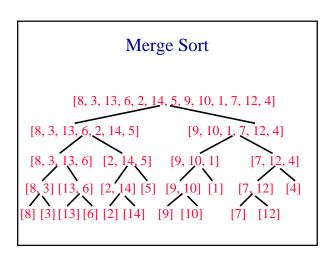


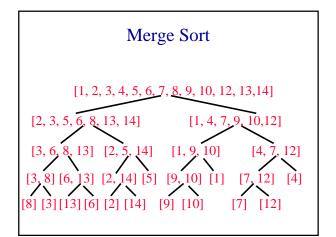
# Merge Two Sorted Lists

A = (5, 6) B = (3, 8, 9, 10) C = (1, 2)
A = (5, 6) B = (8, 9, 10) C = (1, 2, 3)
A = (6) B = (8, 9, 10) C = (1, 2, 3, 5)

# Merge Two Sorted Lists

- A = ()
  - B = (8, 9, 10)
  - C = (1, 2, 3, 5, 6)
- When one of A and B becomes empty, append the other list to C.
- O(1) time needed to move an element into C.
- Total time is O(n + m), where n and m are, respectively, the number of elements initially in A and B.





## Time Complexity

- Let t(n) be the time required to sort n elements.
- t(0) = t(1) = c, where c is a constant.
- When n > 1,
   t(n) = t(ceil(n/2)) + t(floor(n/2)) + dn,
   where d is a constant.
- To solve the recurrence, assume **n** is a power of 2 and use repeated substitution.
- $t(n) = O(n \log n)$ .

# Merge Sort

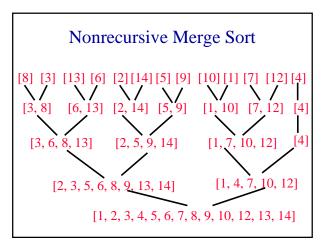
- Downward pass over the recursion tree.
  Divide large instances into small ones.
- Upward pass over the recursion tree.
  - Merge pairs of sorted lists.
- Number of leaf nodes is **n**.
- Number of nonleaf nodes is n-1.

## **Time Complexity**

- · Downward pass.
  - O(1) time at each node.
  - O(n) total time at all nodes.
- Upward pass.
  - O(n) time merging at each level that has a nonleaf node.
  - Number of levels is O(log n).
  - Total time is O(n log n).

## Nonrecursive Version

- Eliminate downward pass.
- Start with sorted lists of size 1 and do pairwise merging of these sorted lists as in the upward pass.



# Complexity

- Sorted segment size is 1, 2, 4, 8, ...
- Number of merge passes is ceil(log<sub>2</sub>n).
- Each merge pass takes O(n) time.
- Total time is O(n log n).
- Need O(n) additional space for the merge.
- Merge sort is slower than insertion sort when n
   <= 15 (approximately). So define a small instance to be an instance with n <= 15.</li>
- Sort small instances using insertion sort.
- Start with segment size = 15.

# Natural Merge Sort

- Initial sorted segments are the naturally ocurring sorted segments in the input.
- Input = [8, 9, 10, 2, 5, 7, 9, 11, 13, 15, 6, 12, 14].
- Initial segments are:
  [8, 9, 10] [2, 5, 7, 9, 11, 13, 15] [6, 12, 14]
- 2 (instead of 4) merge passes suffice.
- Segment boundaries have a[i] > a[i+1].

## Quick Sort

- Small instance has n <= 1. Every small instance is a sorted instance.
- To sort a large instance, select a pivot element from out of the n elements.
- Partition the n elements into 3 groups left, middle and right.
- The middle group contains only the pivot element.
- All elements in the left group are <= pivot.
- All elements in the right group are >= pivot.
- Sort left and right groups recursively.
- Answer is sorted left group, followed by middle group followed by sorted right group.

## Example

#### **6** 2 8 5 11 10 4 1 9 7 3

Use 6 as the pivot.

2 5 4 1 3 6 7 9 10 11 8

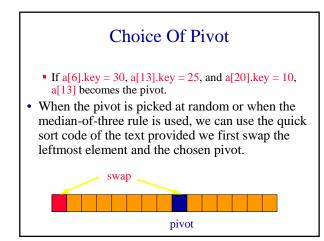
Sort left and right groups recursively.

## Choice Of Pivot

- Pivot is leftmost element in list that is to be sorted.
  - When sorting a[6:20], use a[6] as the pivot.
  - Text implementation does this.
- Randomly select one of the elements to be sorted as the pivot.
  - When sorting a[6:20], generate a random number r in the range [6, 20]. Use a[r] as the pivot.

## **Choice Of Pivot**

- Median-of-Three rule. From the leftmost, middle, and rightmost elements of the list to be sorted, select the one with median key as the pivot.
  - When sorting a[6:20], examine a[6], a[13] ((6+20)/2), and a[20]. Select the element with median (i.e., middle) key.
  - If a[6].key = 30, a[13].key = 2, and a[20].key = 10, a[20] becomes the pivot.
  - If a[6].key = 3, a[13].key = 2, and a[20].key = 10, a[6] becomes the pivot.



# Partitioning Into Three Groups

- Sort a = [6, 2, 8, 5, 11, 10, 4, 1, 9, 7, 3].
- Leftmost element (6) is the pivot.
- When another array **b** is available:
  - Scan a from left to right (omit the pivot in this scan), placing elements <= pivot at the left end of b and the remaining elements at the right end of b.
  - The pivot is placed at the remaining position of the **b**.

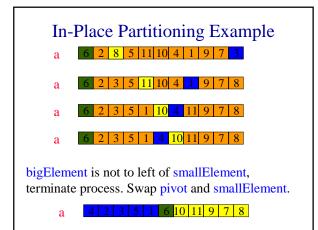
Partitioning Example Using Additional Array

- a 6 2 8 5 11 10 4 1 9 7 3
- b 2 5 4 1 3 6 7 9 10 11 8

Sort left and right groups recursively.

# **In-place Partitioning**

- Find leftmost element (bigElement) > pivot.
- Find rightmost element (smallElement) < pivot.
- Swap bigElement and smallElement provided bigElement is to the left of smallElement.
- Repeat.



# Complexity

- O(n) time to partition an array of n elements.
- Let t(n) be the time needed to sort n elements.
- t(0) = t(1) = c, where c is a constant.
- When t > 1,
   t(n) = t(|left|) + t(|right|) + dn,
   where d is a constant.
- t(n) is maximum when either |left| = 0 or |right| = 0 following each partitioning.

# Complexity

- This happens, for example, when the pivot is always the smallest element.
- For the worst-case time,

### t(n) = t(n-1) + dn, n > 1

- Use repeated substitution to get  $t(n) = O(n^2)$ .
- The best case arises when |left| and |right| are equal (or differ by 1) following each partitioning.
- For the best case, the recurrence is the same as for merge sort.

# Complexity Of Quick Sort

- So the best-case complexity is O(n log n).
- Average complexity is also O(n log n).
- To help get partitions with almost equal size, change in-place swap rule to:
  - Find leftmost element (bigElement) >= pivot.
  - Find rightmost element (smallElement) <= pivot.
  - Swap bigElement and smallElement provided bigElement is to the left of smallElement.
- O(n) space is needed for the recursion stack. May be reduced to O(log n) (see Exercise 19.22).

# Complexity Of Quick Sort

• To improve performance, define a small instance to be one with n <= 15 (say) and sort small instances using insertion sort.

## java.util.arrays.sort

- Arrays of a primitive data type are sorted using quick sort.
  - n < 7 => insertion sort
  - 7 <= n <= 40 => median of three
  - n > 40 => pseudo median of 9 equally spaced elements
     divide the 9 elements into 3 groups
    - find the median of each group
    - pivot is median of the 3 group medians

# java.util.arrays.sort

- Arrays of a nonprimitive data type are sorted using merge sort.
  - n < 7 => insertion sort
  - skip merge when last element of left segment is <= first element of right segment</p>
- Merge sort is stable (relative order of elements with equal keys is not changed).
- Quick sort is not stable.