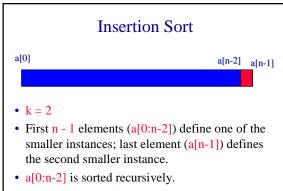
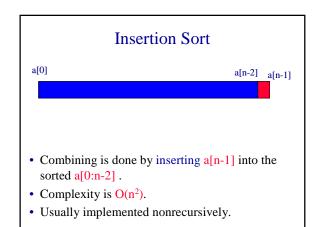


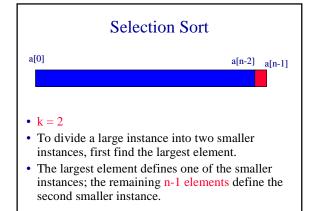
• Small instance.

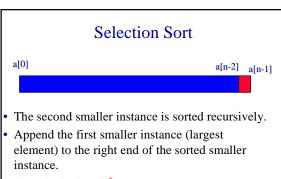
- n <= 1 elements.
- $n \le 10$ elements.
- We'll use n <= 1 for now.
- Large instance.
 - Divide into k >= 2 smaller instances.
 - k = 2, 3, 4, … ?
 - What does each smaller instance look like?
 - Sort smaller instances recursively.
 - How do you combine the sorted smaller instances?



• a[n-1] is a small instance.







- Complexity is O(n²).
- Usually implemented nonrecursively.

Bubble Sort

- Bubble sort may also be viewed as a k = 2 divideand-conquer sorting method.
- Insertion sort, selection sort and bubble sort divide a large instance into one smaller instance of size n - 1 and another one of size 1.
- All three sort methods take $O(n^2)$ time.

Divide And Conquer

- Divide-and-conquer algorithms generally have best complexity when a large instance is divided into smaller instances of approximately the same size.
- When k = 2 and n = 24, divide into two smaller instances of size 12 each.
- When k = 2 and n = 25, divide into two smaller instances of size 13 and 12, respectively.

Merge Sort

- k = 2
- First ceil(n/2) elements define one of the smaller instances; remaining floor(n/2) elements define the second smaller instance.
- Each of the two smaller instances is sorted recursively.
- The sorted smaller instances are combined using a process called merge.
- Complexity is O(n log n).
- Usually implemented nonrecursively.

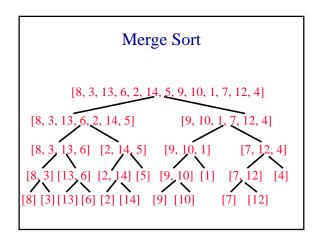
Merge Two Sorted Lists

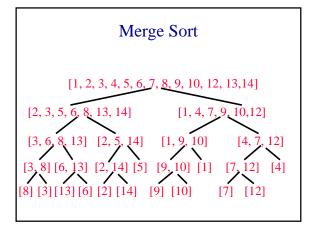
- A = (2, 5, 6) B = (1, 3, 8, 9, 10)
- **C** = ()
- Compare smallest elements of A and B and merge smaller into C.
- A = (2, 5, 6) B = (3, 8, 9, 10) C = (1)

Merge Two Sorted Lists
• $A = (5, 6)$
B = (3, 8, 9, 10)
C = (1, 2)
• $A = (5, 6)$
B = (8, 9, 10)
C = (1, 2, 3)
• $A = (6)$
B = (8, 9, 10)
C = (1, 2, 3, 5)

Merge Two Sorted Lists

- A = () B = (8, 9, 10)
 - C = (1, 2, 3, 5, 6)
- When one of A and B becomes empty, append the other list to C.
- O(1) time needed to move an element into C.
- Total time is O(n + m), where n and m are, respectively, the number of elements initially in A and B.







Time Complexity

- Let t(n) be the time required to sort n elements.
- t(0) = t(1) = c, where c is a constant.
- When n > 1,
 t(n) = t(ceil(n/2)) + t(floor(n/2)) + dn,
 where d is a constant.
- To solve the recurrence, assume **n** is a power of 2 and use repeated substitution.
- $t(n) = O(n \log n)$.

Merge Sort

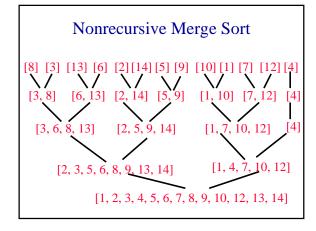
- Downward pass over the recursion tree.
 Divide large instances into small ones.
- Upward pass over the recursion tree.
 - Merge pairs of sorted lists.
- Number of leaf nodes is **n**.
- Number of nonleaf nodes is n-1.

Time Complexity

- Downward pass.
 - O(1) time at each node.
 - O(n) total time at all nodes.
- Upward pass.
 - O(n) time merging at each level that has a nonleaf node.
 - Number of levels is O(log n).
 - Total time is O(n log n).

Nonrecursive Version

- Eliminate downward pass.
- Start with sorted lists of size 1 and do pairwise merging of these sorted lists as in the upward pass.





Complexity

- Sorted segment size is 1, 2, 4, 8, ...
- Number of merge passes is ceil(log₂n).
- Each merge pass takes O(n) time.
- Total time is O(n log n).
- Need O(n) additional space for the merge.
- Merge sort is slower than insertion sort when n
 = 15 (approximately). So define a small instance to be an instance with n <= 15.
- Sort small instances using insertion sort.
- Start with segment size = 15.

Natural Merge Sort

- Initial sorted segments are the naturally ocurring sorted segments in the input.
- Input = [8, 9, 10, 2, 5, 7, 9, 11, 13, 15, 6, 12, 14].
- Initial segments are: [8, 9, 10] [2, 5, 7, 9, 11, 13, 15] [6, 12, 14]
- 2 (instead of 4) merge passes suffice.
- Segment boundaries have a[i] > a[i+1].

Quick Sort

- Small instance has n <= 1. Every small instance is a sorted instance.
- To sort a large instance, select a pivot element from out of the n elements.
- Partition the n elements into 3 groups left, middle and right.
- The middle group contains only the pivot element.
- All elements in the left group are <= pivot.
- All elements in the right group are >= pivot.
- Sort left and right groups recursively.
- Answer is sorted left group, followed by middle group followed by sorted right group.

Example

6 2 8 5 11 10 4 1 9 7 3

Use 6 as the pivot.

2 5 4 1 3 6 7 9 10 11 8

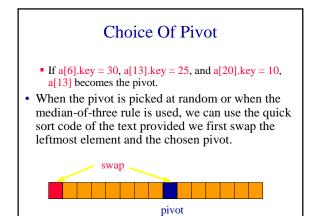
Sort left and right groups recursively.

Choice Of Pivot

- Pivot is leftmost element in list that is to be sorted.
 - When sorting a[6:20], use a[6] as the pivot.
 - Text implementation does this.
- Randomly select one of the elements to be sorted as the pivot.
 - When sorting a[6:20], generate a random number r in the range [6, 20]. Use a[r] as the pivot.

Choice Of Pivot

- Median-of-Three rule. From the leftmost, middle, and rightmost elements of the list to be sorted, select the one with median key as the pivot.
 - When sorting a[6:20], examine a[6], a[13] ((6+20)/2), and a[20]. Select the element with median (i.e., middle) key.
 - If a[6].key = 30, a[13].key = 2, and a[20].key = 10, a[20] becomes the pivot.
 - If a[6].key = 3, a[13].key = 2, and a[20].key = 10, a[6] becomes the pivot.





Partitioning Into Three Groups

- Sort a = [6, 2, 8, 5, 11, 10, 4, 1, 9, 7, 3].
- Leftmost element (6) is the pivot.
- When another array **b** is available:
 - Scan a from left to right (omit the pivot in this scan), placing elements <= pivot at the left end of b and the remaining elements at the right end of b.
 - The pivot is placed at the remaining position of the **b**.

Partitioning Example Using Additional Array

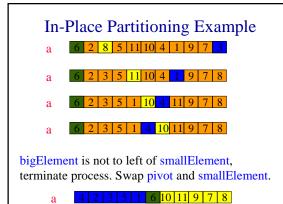
a 6 2 8 5 11 10 4 1 9 7 3

b 2 5 4 1 3 6 7 9 10 11 8

Sort left and right groups recursively.

In-place Partitioning

- Find leftmost element (bigElement) > pivot.
- Find rightmost element (smallElement) < pivot.
- Swap bigElement and smallElement provided bigElement is to the left of smallElement.
- Repeat.



Complexity

- O(n) time to partition an array of n elements.
- Let t(n) be the time needed to sort n elements.
- t(0) = t(1) = c, where c is a constant.
- When t > 1,
 - t(n) = t(|left|) + t(|right|) + dn,
 - where **d** is a constant.
- t(n) is maximum when either |left| = 0 or |right| = 0 following each partitioning.

Complexity

- This happens, for example, when the **pivot** is always the smallest element.
- For the worst-case time, t(n) = t(n-1) + dn, n > 1
- Use repeated substitution to get $t(n) = O(n^2)$.
- The best case arises when |left| and |right| are equal (or differ by 1) following each partitioning.
- For the best case, the recurrence is the same as for merge sort.

Complexity Of Quick Sort

- So the best-case complexity is O(n log n).
- Average complexity is also O(n log n).
- To help get partitions with almost equal size, change in-place swap rule to:
 - Find leftmost element (bigElement) >= pivot.
 - Find rightmost element (smallElement) <= pivot.
 - Swap bigElement and smallElement provided bigElement is to the left of smallElement.
- O(n) space is needed for the recursion stack. May be reduced to O(log n) (see Exercise 19.22).

Complexity Of Quick Sort

• To improve performance, define a small instance to be one with n <= 15 (say) and sort small instances using insertion sort.

java.util.arrays.sort

- Arrays of a primitive data type are sorted using quick sort.
 - n < 7 => insertion sort
 - 7 <= n <= 40 => median of three
 - $n > 40 \Rightarrow$ pseudo median of 9 equally spaced elements
 - divide the 9 elements into 3 groupsfind the median of each group
 - pivot is median of the 3 group medians

java.util.arrays.sort

- Arrays of a nonprimitive data type are sorted using merge sort.
 - n < 7 => insertion sort
 - skip merge when last element of left segment is <= first element of right segment</p>
- Merge sort is stable (relative order of elements with equal keys is not changed).
- Quick sort is not stable.