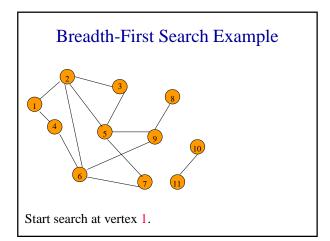


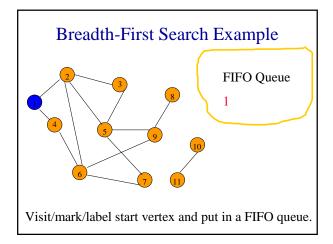
Graph Search Methods

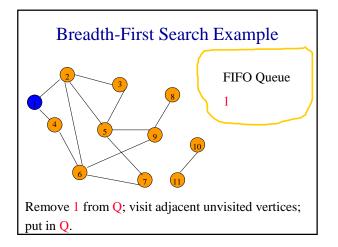
- Many graph problems solved using a search method.
 - Path from one vertex to another.
 - Is the graph connected?
 - Find a spanning tree.
 - Etc.
- Commonly used search methods:
 - Breadth-first search.
 - Depth-first search.

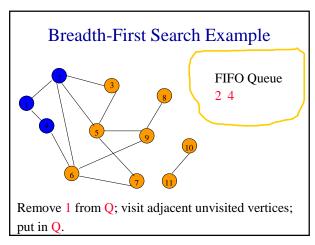
Breadth-First Search

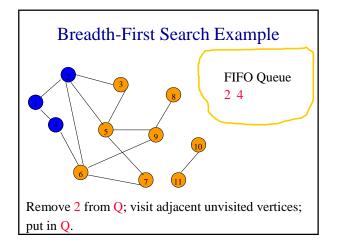
- Visit start vertex and put into a FIFO queue.
- Repeatedly remove a vertex from the queue, visit its unvisited adjacent vertices, put newly visited vertices into the queue.

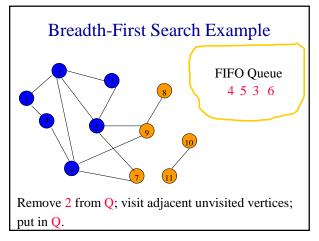


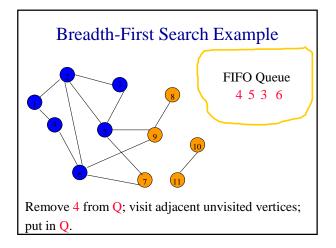


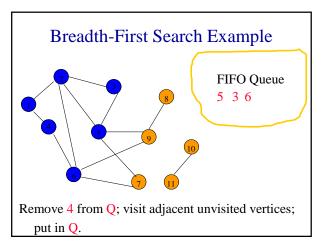


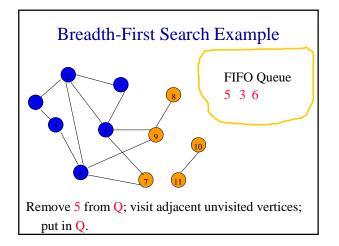


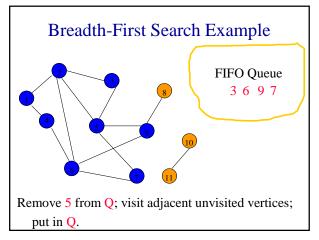


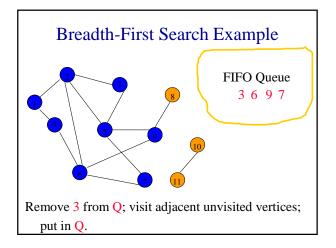


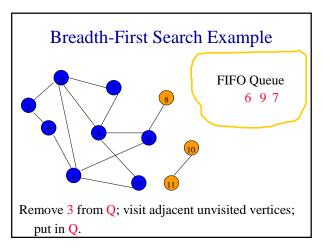


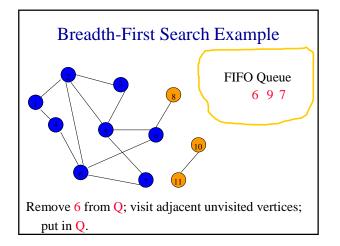


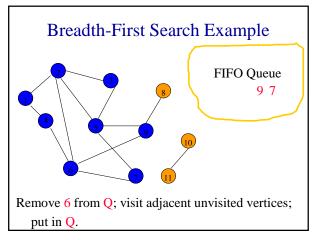


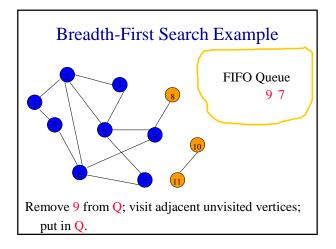


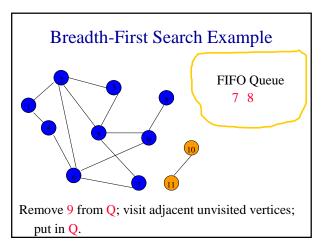


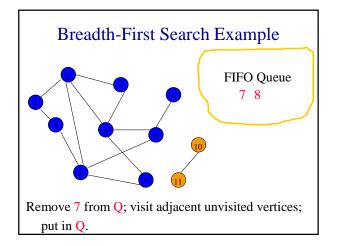


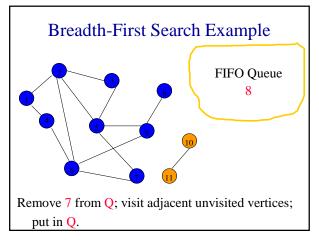


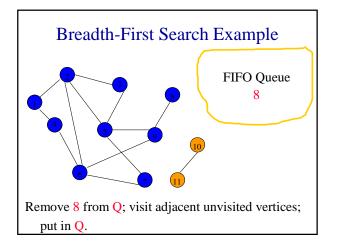


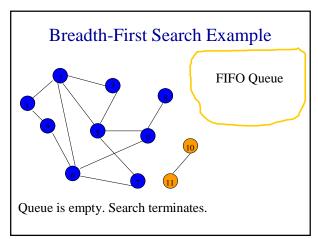














• All vertices reachable from the start vertex (including the start vertex) are visited.

Time Complexity

- Each visited vertex is put on (and so removed from) the queue exactly once.
- When a vertex is removed from the queue, we examine its adjacent vertices.
 - O(n) if adjacency matrix used
 - O(vertex degree) if adjacency lists used
- Total time
 - O(mn), where m is number of vertices in the component that is searched (adjacency matrix)

Time Complexity

- O(n + sum of component vertex degrees) (adj. lists)
- = O(n + number of edges in component)

Path From Vertex v To Vertex u

- Start a breadth-first search at vertex v.
- Terminate when vertex **u** is visited or when Q becomes empty (whichever occurs first).

• Time

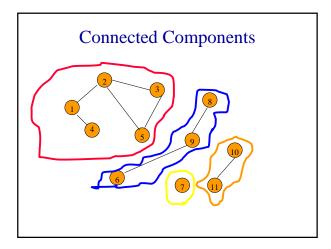
- O(n²) when adjacency matrix used
- O(n+e) when adjacency lists used (e is number of edges)



- Start a breadth-first search at any vertex of the graph.
- Graph is connected iff all **n** vertices get visited.
- Time
 - O(n²) when adjacency matrix used
 - O(n+e) when adjacency lists used (e is number of edges)

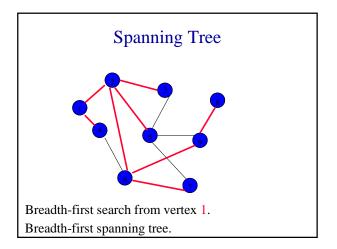
Connected Components

- Start a breadth-first search at any as yet unvisited vertex of the graph.
- Newly visited vertices (plus edges between them) define a component.
- Repeat until all vertices are visited.



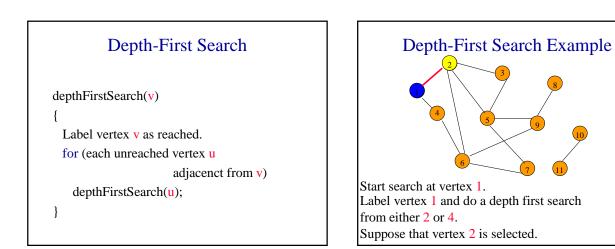


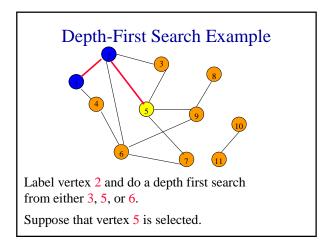
- O(n²) when adjacency matrix used
- O(n+e) when adjacency lists used (e is number of edges)

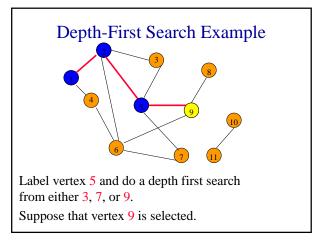


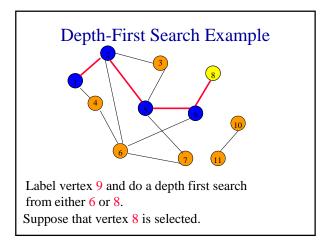


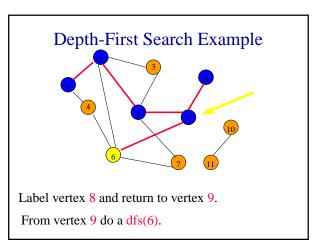
- Start a breadth-first search at any vertex of the graph.
- If graph is connected, the n-1 edges used to get to unvisited vertices define a spanning tree (breadth-first spanning tree).
- Time
 - O(n²) when adjacency matrix used
 - O(n+e) when adjacency lists used (e is number of edges)

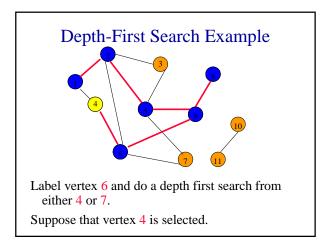


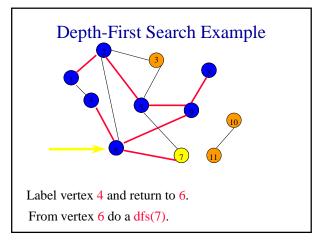


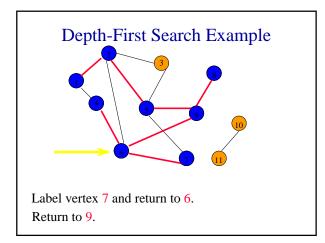


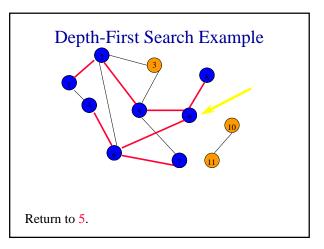


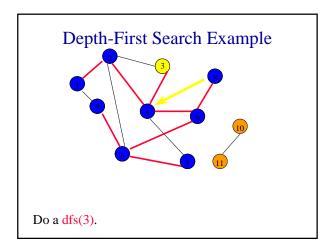


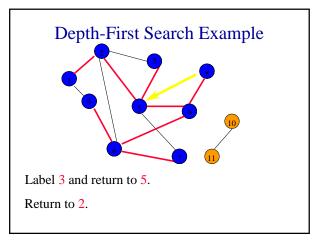


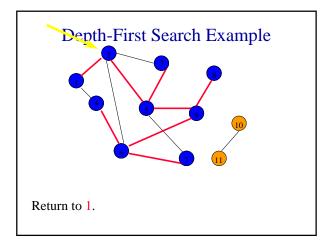


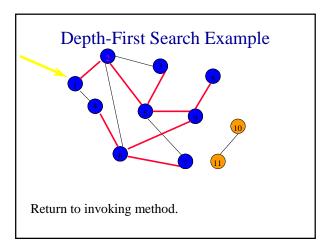












Depth-First Search Properties

- Same complexity as BFS.
- Same properties with respect to path finding, connected components, and spanning trees.
- Edges used to reach unlabeled vertices define a depth-first spanning tree when the graph is connected.
- There are problems for which bfs is better than dfs and vice versa.